

Review of Numerical Analysis

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Computational Fluid Dynamics

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Outline

- Review last week
- Numerical analysis basics
 - Derivative expressions
 - Round-off and truncation errors
 - Order of the error
 - Solutions of ordinary differential equation boundary value problems
 - Finite differences and finite elements
 - Accuracy of results

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2

Turbulence Models

- Cannot compute turbulence exactly except for simple flows
 - Need to use turbulence models
 - Based on combination of theory and empirical measurements
 - Many models available
 - No model correct for all flows
 - Basic approach is to model turbulent viscosity
 - Averages of turbulent fluctuation products are assumed to be proportional to mean gradients

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3

General Equation

- Reynolds (time) averaged Navier-Stokes

$$\frac{\partial(u_i \bar{\varphi} + \overline{u_i \varphi'})}{\partial x_i} = \frac{\partial}{\partial x_i} \gamma^{(\varphi)} \frac{\partial \bar{\varphi}}{\partial x_i} \Rightarrow \frac{\partial u_i \bar{\varphi}}{\partial x_i} = \frac{\partial}{\partial x_i} (\gamma^{(\varphi)} + \gamma_i^{(\varphi)}) \frac{\partial \bar{\varphi}}{\partial x_i}$$

$$\frac{\partial \overline{u_i u_j}}{\partial x_i} = -\frac{1}{\rho} \frac{\partial \bar{p}}{\partial x_i} + \frac{\partial}{\partial x_i} (\nu + \nu_t) \frac{\partial \bar{u}_j}{\partial x_i} \quad \frac{\partial \overline{u_i \varphi}}{\partial x_i} = \frac{\partial}{\partial x_i} \left(\gamma_{lam}^{(\varphi)} + \frac{\nu_t}{\sigma_t^{(\varphi)}} \right) \frac{\partial \bar{\varphi}}{\partial x_i}$$
- Turbulence models obtain values for ν_t
 - Dimensionally $\nu_t = C \mid V$, e.g., $C_\mu (k^{3/2}/\epsilon) k^{1/2}$
- Turbulent Prandtl number, $\sigma_t^{(\phi)}$, is empirical constant in turbulence models

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4

Model Guidance

- Choosing a model
 - Previous work at your organization or from literature research
 - User's manual for code
 - Use default constants
 - Unusual features: non-equilibrium turbulence, high strain rates, adverse pressure gradients, rotating machinery, compressible flows
 - Check y^+ values for correct spacing with wall functions or laminar sublayer

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5

More Guidance

- Common models
 - k - ϵ standard model and variants for internal simple flows
 - Solve two PDEs
 - Spalart-Allmaras for aerospace applications with wall-bounded flows
 - Only one PDE
 - Reynolds stress model for complex flows
 - Requires solution of seven PDEs
 - Several other models
 - No one right model for all applications

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6

Numerical Analysis

- Want to express derivatives and integrals in terms of discrete data points
- Use different methods
 - Develop interpolation polynomial and integrate or differentiate this result
 - Use Taylor series to get expressions for derivatives
- Want expressions and measure of error with their use

Finite Difference Grids

- Subdivide region into discrete points
- Spacing between the points may be uniform or non-uniform
- Example: grid for $x_{\min} \leq x \leq x_{\max}$ with N+1 nodes numbered from zero to N
- Initial node value, $x_0 = x_{\min}$
- Final grid node value, $x_N = x_{\max}$
- Node spacing between $\Delta x_i = x_i$ and x_{i-1}
- Uniform spacing, $h = \Delta x_i = (x_{\min} - x_{\max})/N$
- N+1 nodes give N spaces

Finite Difference Grids II

- Non-uniform grid illustrated below

$$x_0 \quad x_1 \quad x_2 \quad x_3 \quad x_{N-2} \quad x_{N-1} \quad x_N$$

- Two space dimensions require x and y grids (M+1 y nodes)

$$X_0 = X_{\min} \quad X_N = X_{\max} \quad X_i - X_{i-1} = \Delta X_i$$

$$y_0 = y_{\min} \quad y_M = y_{\max} \quad y_j - y_{j-1} = \Delta y_j$$

- Most general case has three space dimensions (x, y, z, and time)

Finite Difference Grids III

- Grid notation for four independent variables: x, y, z and t

$$x_0 = x_{\min} \quad x_N = x_{\max} \quad x_i - x_{i-1} = \Delta x_i$$

$$y_0 = y_{\min} \quad y_M = y_{\max} \quad y_j - y_{j-1} = \Delta y_j$$

$$Z_0 = Z_{\min} \quad Z_K = Z_{\max} \quad Z_k - Z_{k-1} = \Delta Z_k$$

$$t_0 = t_{\min} \quad t_L = t_{\max} \quad t_n - t_{n-1} = \Delta t_n$$

- Dependent variable $u(x,y,z,t)$ at discrete points $u(x_i, y_j, z_k, t_n)$

- Use notation below for this value of u

$$u_{ijk}^n = u(x_i, y_j, z_k, t_n)$$

Derivative Expressions

- Obtain from differentiating interpolation polynomials or from Taylor series
- Series expansion for $f(x)$ about $x = a$

$$f(x) = f(a) + \left. \frac{df}{dx} \right|_{x=a} (x-a) + \frac{1}{2!} \left. \frac{d^2f}{dx^2} \right|_{x=a} (x-a)^2 + \frac{1}{3!} \left. \frac{d^3f}{dx^3} \right|_{x=a} (x-a)^3 + \dots$$

- Note: $d^0f/dx^0 = f$
and $0! = 1$

$$f(x) = \sum_{n=0}^{\infty} \frac{1}{n!} \left. \frac{d^n f}{dx^n} \right|_{x=a} (x-a)^n$$

- What is error from truncating series?

Truncation Error

- If we truncate series after m terms

$$f(x) = \underbrace{\sum_{n=0}^m \frac{1}{n!} \frac{d^n f}{dx^n} \Big|_{x=a}}_{\text{Terms used}} (x-a)^n + \underbrace{\sum_{n=m+1}^{\infty} \frac{1}{n!} \frac{d^n f}{dx^n} \Big|_{x=a}}_{\text{Truncation error, } \varepsilon_m} (x-a)^n$$

- Can write truncation error as single term at unknown location (derivation based on the theorem of the mean)

$$\varepsilon_m = \sum_{n=m+1}^{\infty} \frac{1}{n!} \left. \frac{d^n f}{dx^n} \right|_{x=a} (x-a)^n = \frac{1}{(m+1)!} \left. \frac{d^{m+1} f}{dx^{m+1}} \right|_{x=a} (x-a)^{m+1}$$

Derivative Expressions

- Look at finite-difference grid with equal spacing: $h = \Delta x$ so $x_i = x_0 + ih$
- Taylor series about $x = x_i$ gives $f(x_i + kh) = f[x_0 + (i+k)h] = f_{i+k}$ in terms of $f(x_i) = f_i$

$$f(x_i + kh) = f(x_i) + \left. \frac{df}{dx} \right|_{x=x_i} kh + \frac{1}{2!} \left. \frac{d^2 f}{dx^2} \right|_{x=x_i} (kh)^2 + \frac{1}{3!} \left. \frac{d^3 f}{dx^3} \right|_{x=x_i} (kh)^3 + \dots$$

- Compact derivative notation

$$f'_i = \left. \frac{df}{dx} \right|_{x=x_i} \quad f''_i = \left. \frac{d^2 f}{dx^2} \right|_{x=x_i} \quad \dots \quad f^{(n)}_i = \left. \frac{d^n f}{dx^n} \right|_{x=x_i}$$

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13

Derivative Expressions II

- Combine all definitions for compact series notation

$$f(x_i + kh) = f(x_i) + \left. \frac{df}{dx} \right|_{x=x_i} kh + \frac{1}{2!} \left. \frac{d^2 f}{dx^2} \right|_{x=x_i} (kh)^2 + \frac{1}{3!} \left. \frac{d^3 f}{dx^3} \right|_{x=x_i} (kh)^3 + \dots$$

$$f_{i+k} = f_i + f'_i kh + \frac{f''_i (kh)^2}{2!} + \frac{f'''_i (kh)^3}{3!} + \dots$$

- Use this formula to get expansions for various grid locations about $x = x_i$ and use results to get derivative expressions

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14

Derivative Expressions III

- Apply general equation for $k = 1$ and $k = -1$

$$f_{i+k} = f_i + f'_i kh + \frac{f''_i (kh)^2}{2!} + \frac{f'''_i (kh)^3}{3!} + \dots$$

$$f_{i+1} = f_i + f'_i h + \frac{f''_i h^2}{2!} + \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i-1} = f_i - f'_i h + \frac{f''_i h^2}{2!} - \frac{f'''_i h^3}{3!} + \dots$$

$$f'_i = \frac{f_{i+1} - f_{i-1}}{h} - \frac{f''_i h}{2!} + \frac{f'''_i h}{3!} - \dots = \frac{f_{i+1} - f_{i-1}}{h} + Ah \quad \text{Forward}$$

$$f'_i = \frac{f_i - f_{i-1}}{h} + \frac{f''_i h}{2!} - \frac{f'''_i h}{3!} + \dots = \frac{f_i - f_{i-1}}{h} + Ah \quad \text{Backward}$$

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15

Derivative Expressions IV

- Subtract f_{i+1} and f_{i-1} expressions

$$f_{i+1} = f_i + f'_i h + \frac{f''_i h^2}{2!} + \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i-1} = f_i - f'_i h + \frac{f''_i h^2}{2!} - \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i+1} - f_{i-1} = 2f'_i h + \frac{2f'''_i h^3}{3!} + \frac{2f^{(5)}_i h^5}{5!} + \dots \quad \text{Solve this result for } f'_i$$

$$f'_i = \frac{f_{i+1} - f_{i-1}}{h} + \frac{f'''_i h^2}{3!} + \frac{f^{(5)}_i h^4}{5!} - \dots = \frac{f_{i+1} - f_{i-1}}{2h} + Ah^2$$

- Result called central difference expression

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16

Error in Arithmetic Mean

- Add f_{i+1} and f_{i-1} expressions

$$f_{i+1} = f_i + f'_i h + \frac{f''_i h^2}{2!} + \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i-1} = f_i - f'_i h + \frac{f''_i h^2}{2!} - \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i+1} + f_{i-1} = 2f_i + \frac{2f''_i h^2}{2!} + \frac{2f^{(4)}_i h^4}{4!} + \dots \quad \text{Solve this result for } f_i$$

$$f_i = \frac{f_{i+1} + f_{i-1}}{2} + \frac{f''_i h^2}{2!} + \frac{f^{(4)}_i h^4}{4!} - \dots = \frac{f_{i+1} + f_{i-1}}{2} + Ah^2$$

- Shows error in use of arithmetic mean

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17

Order of the Error

- Forward and backward derivative have error term that is proportional to h
- Central difference error is proportional to h^2
- Error proportional to h^n called n^{th} order
- Reducing step size by a factor of a reduces n^{th} order error by a^n

$$\mathcal{E}_2 \approx \mathcal{E}_1 \left(\frac{h_2}{h_1} \right)^n$$

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18

Order of the Error Notation

- Write the error term for n^{th} error term as $O(h^n)$
 - Big oh notation, O, denotes order
 - Recognizes that factor multiplying h^n may change slightly with h

First order forward

$$f'_i = \frac{f_{i+1} - f_i}{h} + O(h)$$

First order backward

$$f'_i = \frac{f_i - f_{i-1}}{h} + O(h)$$

Second order central

$$f'_i = \frac{f_{i+1} - f_{i-1}}{2h} + O(h^2)$$

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19

Higher Order Derivatives

- Add f_{i+1} and f_{i-1} expressions

$$f_{i+1} = f_i + f'_i h + \frac{f''_i h^2}{2!} + \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i-1} = f_i - f'_i h + \frac{f''_i h^2}{2!} - \frac{f'''_i h^3}{3!} + \dots$$

$$f_{i+1} + f_{i-1} = 2f_i + 2\frac{f''_i h^2}{2!} + \frac{2f'''_i h^4}{4!} + \frac{2f^{(4)}_i h^6}{6!} + \dots$$

$$f''_i = \frac{f_{i+1} + f_{i-1} - 2f_i}{h^2} + \frac{f''_i h^2}{3!} + \frac{f'''_i h^4}{5!} - \dots = \frac{f_{i+1} + f_{i-1} - 2f_i}{h^2} + O(h^2)$$

- f'' is second-order, central difference

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20

Higher Order Directional

- We can get higher order derivative expressions at the expense of more computations
- Get second order forward and backward derivative expressions from f_{i+2} and f_{i-2} , respectively
- Combine with previous expressions for f_{i+1} and f_{i-1} to eliminate first order error term

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21

Specific Taylor Series

- General equation $f_{i+k} = f_i + f'_i kh + \frac{f''_i (kh)^2}{2!} + \frac{f'''_i (kh)^3}{3!} + \dots$

$$k = 2 \quad f_{i+2} = f_i + 2f'_i h + 4\frac{f''_i h^2}{2!} + 8\frac{f'''_i h^3}{3!} + \dots$$

$$k = -2 \quad f_{i-2} = f_i - 2f'_i h + 4\frac{f''_i h^2}{2!} - 8\frac{f'''_i h^3}{3!} + \dots$$

$$k = 3 \quad f_{i+3} = f_i + 3f'_i h + 9\frac{f''_i h^2}{2!} + 27\frac{f'''_i h^3}{3!} + \dots$$

$$k = -3 \quad f_{i-3} = f_i - 3f'_i h + 9\frac{f''_i h^2}{2!} - 27\frac{f'''_i h^3}{3!} + \dots$$

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22

Second Order Forward

- Subtract $4f_{i+1}$ from f_{i+2} to eliminate h^2 term

$$f_{i+2} - 4f_{i+1} = \left[f_i + 2f'_i h + 4f''_i \frac{h^2}{2} + 8f'''_i \frac{h^3}{6} + \dots \right]$$

$$-4 \left[f_i + f'_i h + f''_i \frac{h^2}{2} + f'''_i \frac{h^3}{6} + \dots \right]$$

$$f_{i+2} - 4f_{i+1} + 3f_i = -2hf'_i + 4f'''_i \frac{h^3}{6} + \dots$$

$$f'_i = \frac{-f_{i+2} + 4f_{i+1} - 3f_i}{2h} + f'''_i \frac{h^2}{3} + \dots$$

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23

Second Order Backwards

- Add $4f_{i-1}$ to $-f_{i-2}$ to eliminate h^2 term

$$-f_{i-2} + 4f_{i-1} = \left[f_i - 2f'_i h + 4f''_i \frac{h^2}{2} - 8f'''_i \frac{h^3}{6} + \dots \right]$$

$$+4 \left[f_i - f'_i h + f''_i \frac{h^2}{2} - f'''_i \frac{h^3}{6} + \dots \right]$$

$$-f_{i-2} + 4f_{i-1} - 3f_i = -2hf'_i + 4f'''_i \frac{h^3}{6} + \dots$$

$$f'_i = \frac{-f_{i-2} + 4f_{i-1} - 3f_i}{2h} + f'''_i \frac{h^2}{3} + \dots$$

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24

Other Derivative Expressions

- Can continue in this fashion
 - Write Taylor series for f_{i+1} , f_{i-1} , f_{i+2} , f_{i-2} , f_{i+3} , f_{i-3} , etc.
 - Create linear combinations with factors that eliminate desired terms
 - Eliminate f_i term to obtain central difference
 - Keep only terms in f_k with $k \geq i$ for forward difference expressions
 - Keep only terms in f_k with $k \leq i$ for backward difference expressions
 - See results for different expressions in common numerical analysis texts

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25

Order of Error Examples

- Table 2-1 in notes shows error in first derivative for e^x around $x = 1$
 - Using first- and second-order forward and second-order central differences
 - Step $h = 0.4, 0.2$, and 0.1
 - Error ratio for doubling step size
 - 4.01 to 4.02 for central differences
 - 2.07 to 2.15 for first-order forward differences
 - 4.32 to 4.69 for second-order forward

$$n \approx \frac{\log\left(\frac{\varepsilon_2}{\varepsilon_1}\right)}{\log\left(\frac{h_2}{h_1}\right)} = \frac{\log(\varepsilon_2) - \log(\varepsilon_1)}{\log(h_2) - \log(h_1)}$$

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26

Roundoff Error

- Possible in derivative expressions from subtracting close differences
- Example $f(x) = e^x$: $f'(x) \approx (e^{x+h} - e^{x-h})/(2h)$ and error at $x = 1$ is $(e^{1+h} - e^{1-h})/(2h) - e$

$$E = \frac{3.004166 - 2.722815}{2(0.1)} - 2.718282 = 4.5 \times 10^{-3}$$

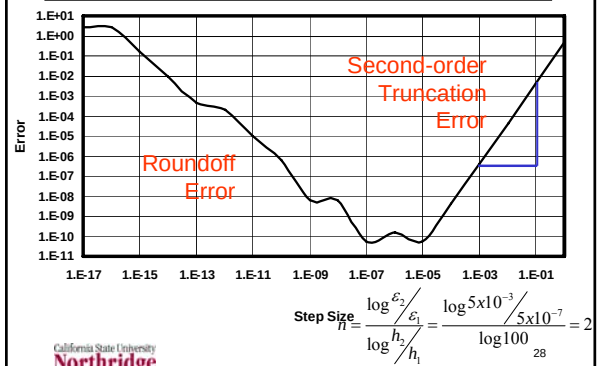
$$E = \frac{2.7185536702 - 2.7180100139}{2(0.0001)} - 2.718281828459 = 4.5 \times 10^{-9}$$

$$E = \frac{2.71828210028724 - 2.71828155660388}{2(0.0000001)} - 2.718281828 = 5.9 \times 10^{-9}$$

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27

Figure 2-1. Effect of Step Size on Error



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Uneven Step Sizes

- Apply general Taylor series for $f_k = f(x_k)$ in terms of $f_i = f(x_i)$ for $k = i + 1$ and $k = i - 1$

$$f_k = f_i + f'_i(x_k - x_i) + \frac{f''_i}{2!}(x_k - x_i)^2 + \frac{f'''_i}{3!}(x_k - x_i)^3 + \dots$$

$$f_{i+1} = f_i + f'_i(x_{i+1} - x_i) + \frac{f''_i}{2!}(x_{i+1} - x_i)^2 + \frac{f'''_i}{3!}(x_{i+1} - x_i)^3 + \dots$$

$$f_{i-1} = f_i + f'_i(x_{i-1} - x_i) + \frac{f''_i}{2!}(x_{i-1} - x_i)^2 + \frac{f'''_i}{3!}(x_{i-1} - x_i)^3 + \dots$$

- Subtract (or add) the last two equations to get an expression for f'_i (or f_i)

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29

First Derivative

- Solve subtraction for f'_i and rearrange

$$f_{i+1} - f_{i-1} = f'_i[(x_{i+1} - x_i) - (x_{i-1} - x_i)] + \frac{f''_i}{2!}[(x_{i+1} - x_i)^2 - (x_{i-1} - x_i)^2] + \frac{f'''_i}{3!}[(x_{i+1} - x_i)^3 - (x_{i-1} - x_i)^3] + \dots$$

$$f'_i = \frac{f_{i+1} - f_{i-1}}{x_{i+1} - x_{i-1}} - \frac{f''_i}{2!} \frac{(x_{i+1} - x_i)^2 - (x_{i-1} - x_i)^2}{x_{i+1} - x_{i-1}} - \frac{f'''_i}{3!} \frac{(x_{i+1} - x_i)^3 - (x_{i-1} - x_i)^3}{x_{i+1} - x_{i-1}} + \dots$$

- If $x_{i+1} - x_i = x_i - x_{i-1} = h$, we have second order central difference
- Uneven step size gives first order error of $f'_i[(x_{i+1} - x_i) - (x_i - x_{i-1})]/[2(x_{i+1} - x_{i-1})]$

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30

Arithmetic Mean

- Solve addition for f_i and rearrange

$$f_{i+1} + f_{i-1} = 2f_i + f_i'[(x_{i+1} - x_i) + (x_{i-1} - x_i)] + \frac{f_i''}{2!}[(x_{i+1} - x_i)^2 + (x_{i-1} - x_i)^2] + \frac{f_i'''}{3!}[(x_{i+1} - x_i)^3 + (x_{i-1} - x_i)^3] + \dots$$

$$f_i = \frac{f_{i+1} + f_{i-1}}{2} - f_i' \frac{x_{i+1} + x_{i-1} - 2x_i}{2} - \frac{f_i''}{2!} \frac{(x_{i+1} - x_i)^2 + (x_{i-1} - x_i)^2}{2} + \dots$$
- If $x_{i+1} - x_i = x_i - x_{i-1} = h$, we have second order error
- Uneven step size gives first order error of $f_i' (x_{i+1} + x_{i-1} - 2x_i)/2$

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31

Second Derivative

- Start with same equations; subtract $(x_{i+1} - x_i)$ times second equation from $(x_{i-1} - x_i)$ times first equation to eliminate f_i' term

$$f_{i+1} = f_i + f_i'(x_{i+1} - x_i) + \frac{f_i''}{2!}(x_{i+1} - x_i)^2 + \frac{f_i'''}{3!}(x_{i+1} - x_i)^3 + \dots$$

$$f_{i-1} = f_i + f_i'(x_{i-1} - x_i) + \frac{f_i''}{2!}(x_{i-1} - x_i)^2 + \frac{f_i'''}{3!}(x_{i-1} - x_i)^3 + \dots$$

$$(x_{i-1} - x_i)f_{i+1} - (x_{i+1} - x_i)f_{i-1} = (x_{i-1} - x_i)f_i - (x_{i+1} - x_i)f_i$$

$$+ \frac{f_i''}{2!}[(x_{i-1} - x_i)(x_{i+1} - x_i)^2 - (x_{i+1} - x_i)(x_{i-1} - x_i)^2]$$

$$+ \frac{f_i'''}{3!}[(x_{i-1} - x_i)(x_{i+1} - x_i)^3 - (x_{i+1} - x_i)(x_{i-1} - x_i)^3] + \dots$$

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32

Second Derivative II

- Divide by $x_{i+1} - x_i$ and define $r_i = (x_{i+1} - x_i)/(x_i - x_{i-1})$ ($r_i = 1$ for uniform grid)

$$f_{i+1} + r_i f_{i-1} = f_i + r_i f_i + \frac{f_i''}{2!}[(x_{i+1} - x_i)^2 - (x_{i+1} - x_i)(x_{i-1} - x_i)]$$

$$+ \frac{f_i'''}{3!}[(x_{i+1} - x_i)^3 - (x_{i+1} - x_i)(x_{i-1} - x_i)^2] + \dots$$

$$f_i'' = 2 \frac{f_{i+1} + r_i f_{i-1} - (1 + r_i)f_i}{(x_{i+1} - x_i)^2 - (x_{i+1} - x_i)(x_{i-1} - x_i)}$$

$$- \frac{f_i'''}{3} \frac{(x_{i+1} - x_i)^3 - (x_{i+1} - x_i)(x_{i-1} - x_i)^2}{(x_{i+1} - x_i)^2 - (x_{i+1} - x_i)(x_{i-1} - x_i)} + \dots$$

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33

Second Derivative III

- Rearrange individual terms

$$\frac{2}{(x_{i+1} - x_i)^2 - (x_{i+1} - x_i)(x_{i-1} - x_i)} =$$

$$= \frac{1}{(x_i - x_{i-1})^2 \left[\frac{(x_{i+1} - x_i)^2}{(x_i - x_{i-1})^2} + \frac{(x_{i+1} - x_i)}{(x_i - x_{i-1})} \right]} = \frac{1}{(x_i - x_{i-1})^2 \frac{r_i^2 + r_i}{2}}$$

$$\frac{(x_{i+1} - x_i)^3 - (x_{i+1} - x_i)(x_{i-1} - x_i)^2}{(x_{i+1} - x_i)^2 - (x_{i+1} - x_i)(x_{i-1} - x_i)} = \frac{(x_{i+1} - x_i)(1 - r_i^{-2})}{1 + r_i^{-1}}$$

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34

Second Derivative IV

- Result shows first-order truncation error that is zero for equal step sizes ($r_i = 1$)

$$f_i'' = \frac{f_{i+1} + r_i f_{i-1} - (1 + r_i)f_i}{(x_i - x_{i-1})^2 \frac{r_i^2 + r_i}{2}} - \frac{f_i'''}{3} \frac{(x_{i+1} - x_i)(1 - r_i^{-2})}{1 + r_i^{-1}} + \dots$$

- Alternative approach second derivative is first derivative of first derivative

- Apply unequal difference equation for first derivative $f_i' = \frac{f_{i+1} - f_{i-1}}{x_{i+1} - x_{i-1}} + \dots$

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35

Second Derivative V

$$f_i'' = \frac{\frac{df}{dx}\big|_{i+1/2} - \frac{df}{dx}\big|_{i-1/2}}{x_{i+1/2} - x_{i-1/2}} + \dots = \frac{\frac{df}{dx}\big|_{i+1/2} - \frac{df}{dx}\big|_{i-1/2}}{x_{i+1/2} - x_{i-1/2}} + \dots$$

$$= \frac{\frac{f_{i+1} - f_i}{x_{i+1} - x_i} - \frac{f_i - f_{i-1}}{x_i - x_{i-1}}}{\frac{x_{i+1} + x_i}{2} - \frac{x_i + x_{i-1}}{2}} + \dots = 2 \frac{x_{i+1} - x_i}{x_{i+1} - x_{i-1}} \frac{x_i - x_{i-1}}{x_{i+1} - x_{i-1}} + \dots$$

- Can rearrange to show that this gives same result as Taylor series approach

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36

Proof of Same Result

$$f_i'' = 2 \frac{\frac{f_{i+1} - f_i}{\Delta x_{i+1}} - \frac{f_i - f_{i-1}}{\Delta x_i}}{X_{i+1} - X_{i-1}} = 2 \frac{\frac{f_{i+1} - f_i}{\Delta x_{i+1}} - \frac{f_i - f_{i-1}}{\Delta x_i}}{\Delta x_{i+1} + \Delta x_i} \cdot \frac{\Delta x_{i+1}}{\Delta x_i}$$

$$f_i'' = 2 \frac{f_{i+1} - f_i - \frac{\Delta x_{i+1}}{\Delta x_i} (f_i - f_{i-1})}{\left[(\Delta x_{i+1})^2 + \Delta x_i \Delta x_{i+1} \right]} \cdot \frac{\Delta x_i}{(\Delta x_i)^2} = 2 \frac{f_{i+1} + \frac{\Delta x_{i+1}}{\Delta x_i} f_{i-1} - f_i \left(1 + \frac{\Delta x_{i+1}}{\Delta x_i} \right)}{\left[\left(\frac{\Delta x_{i+1}}{\Delta x_i} \right)^2 + \frac{\Delta x_{i+1}}{\Delta x_i} \right]} \cdot \frac{1}{(\Delta x_i)^2}$$

$$f_i'' = \frac{f_{i+1} + r_i f_{i-1} - (1 + r_i) f_i}{(\Delta x_i)^2 \frac{r_i^2 + r_i}{2}}$$

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37

Finite-volume Approach

- Integrate PDE over a small volume
- Where derivatives occur, replace them by finite-difference expressions
- Where source terms occur, replace terms like $\int_{\Delta V} S dV$ by $S_{\text{avg}} \Delta V$
 - S_{avg} is average S for control volume
- Finite Volume grid notation

Variables
defined at
Nodes

Volume
boundaries
at Faces

$$x_W = x_{i-1} \quad x_w = x_{i-1/2} \quad x_P = x_i \quad x_e = x_{i+1/2} \quad x_E = x_{i+1}$$

$$\delta x_{WP} = x_P - x_W, \quad \delta x_{wP} = x_P - x_w, \quad \delta x_{Pe} = x_e - x_P, \quad \delta x_{pE} = x_E - x_P$$

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38

Finite Volume Example

- Consider 1D diffusion and source only

$$\frac{d}{dx} \Gamma \frac{d\phi}{dx} + S = 0 \quad \int \left(\frac{d}{dx} \Gamma \frac{d\phi}{dx} + S \right) dV = \int \left(\frac{d}{dx} \Gamma \frac{d\phi}{dx} + S \right) A dx = 0$$

- Integrate over finite-volume grid

$$x_W = x_{i-1} \quad x_w = x_{i-1/2} \quad x_P = x_i \quad x_e = x_{i+1/2} \quad x_E = x_{i+1}$$

$$\delta x_{WP} = x_P - x_W, \quad \delta x_{wP} = x_P - x_w, \quad \delta x_{Pe} = x_e - x_P, \quad \delta x_{pE} = x_E - x_P$$

$$A \int \frac{d}{dx} \Gamma \frac{d\phi}{dx} dx + \int S dV = A \int_{x_w}^{x_e} d \left(\Gamma \frac{d\phi}{dx} \right) + \bar{S} \Delta V = \left(\Gamma A \frac{d\phi}{dx} \right)_e - \left(\Gamma A \frac{d\phi}{dx} \right)_w + \bar{S} \Delta V = 0$$

- What are Γ and $d\phi/dx$ at w and e faces?

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39

Finite Volume Example II

- Use mean value for coefficient
 - $\Gamma_e = (\Gamma_P + \Gamma_E)/2$ and $\Gamma_w = (\Gamma_W + \Gamma_P)/2$
- Use central difference for $d\phi/dx$
 - $d\phi/dx|_e = (\phi_E - \phi_P)/\delta x$ $d\phi/dx|_w = (\phi_P - \phi_W)/\delta x$
- Substitute into $\left(\Gamma A \frac{d\phi}{dx} \right)_e - \left(\Gamma A \frac{d\phi}{dx} \right)_w + \bar{S} \Delta V = 0$

$$- \text{Define } \bar{S} \Delta V = S_w + S_p \phi_P$$

$$\Gamma_e A_e \frac{\phi_E - \phi_P}{\delta x_{Pe}} - \Gamma_w A_w \frac{\phi_P - \phi_W}{\delta x_{wP}} + S_w + S_p \phi_P = \frac{\Gamma_e A_e \phi_E}{\delta x_{Pe}} + \frac{\Gamma_w A_w \phi_W}{\delta x_{wP}} + S_w - \left(\frac{\Gamma_e A_e}{\delta x_{Pe}} + \frac{\Gamma_w A_w}{\delta x_{wP}} + S_p \right) \phi_P = 0$$

$$- \text{Define } a_E = \frac{\Gamma_e A_e}{\delta x_{Pe}} \quad a_w = \frac{\Gamma_w A_w}{\delta x_{wP}} \quad a_P = \frac{\Gamma_e A_e}{\delta x_{Pe}} + \frac{\Gamma_w A_w}{\delta x_{wP}} - S_p = a_E + a_w - S_p$$

$$a_E \phi_E + a_w \phi_W + S_p - a_P \phi_P = 0 \quad a_E \phi_E + a_w \phi_W - a_P \phi_P = -S_p$$

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40

Finite-Volume Example III

- This represents equation for one node
 - Need to write equations for all nodes
 - Simple for one-dimensional problem
 - Here is where $i, i+1, i-1$ notation is easier
 - $a_{W,i} \phi_{i-1} - a_{P,i} \phi_i + a_{E,i} \phi_{i+1} = -S_{u,i}$
 - Apply this result for nodes from $i = 1$ to $i = N - 1$
 - Nodes $i = 0$ and $i = N$ are boundary conditions
 - Look at constant Γ, A , and δx such that $\Gamma A = 1$
 - Let $S_u = 0$ and $S_p = -10\delta x$ for all nodes

$$a_E = \frac{\Gamma_e A_e}{\delta x_{Pe}} = \frac{1}{\delta x} \quad a_w = \frac{\Gamma_w A_w}{\delta x_{wP}} = \frac{1}{\delta x} \quad a_P = a_E + a_w - S_p = \frac{2}{\delta x} + 10\delta x$$

$$a_E \phi_E + a_w \phi_W - a_P \phi_P = \frac{\phi_{i-1}}{\delta x} - \left(\frac{2}{\delta x} + 10\delta x \right) \phi_i - \frac{\phi_{i+1}}{\delta x} = S_{u,i} = 0 \quad 41$$

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Finite-Volume Example IV

- Need to handle boundary conditions
 - Assume $\phi = 2$ at $x = 0$ and $\phi = 3$ at $x = L = 1$
 - Nodes numbered from 0 to N
 - $x_0 = 0$ and $x_N = L = 1$ (assumed); $\phi_0 = 2$ and $\phi_N = 3$
 - At $i = 1$ (1 node in from left boundary) $\phi_0 - [2 + (\delta x)^2] \phi_1 + \phi_2 = 0$ with $\phi_0 = 2$ gives $-[2 + (\delta x)^2] \phi_1 + \phi_2 = -2$
 - At $i = N - 1$ (1 node in from right boundary) $\phi_{N-2} - [2 + (\delta x)^2] \phi_{N-1} + \phi_N = 0$ with $\phi_N = 3$ gives $\phi_{N-2} - [2 + (\delta x)^2] \phi_{N-1} = -3$

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Finite-Volume Example V

- System of equations to solve

$$\begin{aligned} -2.4\phi_1 + \phi_2 &= -2 \\ \phi_1 - 2.4\phi_2 + \phi_3 &= 0 \\ \phi_2 - 2.4\phi_3 + \phi_4 &= 0 \\ \phi_3 - 2.4\phi_4 &= -3 \end{aligned}$$

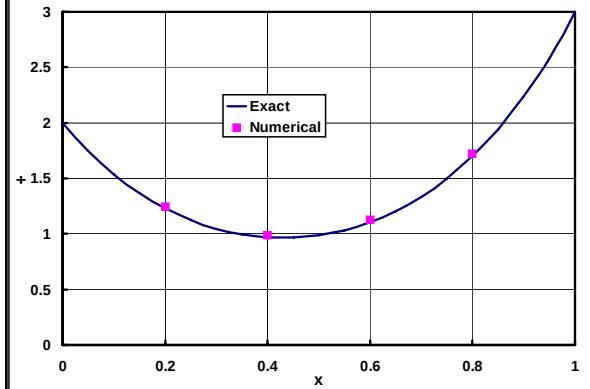
- Matrix form

$$\begin{bmatrix} -2.4 & 1 & 0 & 0 \\ 1 & -2.4 & 1 & 0 \\ 0 & 1 & -2.4 & 1 \\ 0 & 0 & 1 & -2.4 \end{bmatrix} \begin{bmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \\ \phi_4 \end{bmatrix} = \begin{bmatrix} -2 \\ 0 \\ 0 \\ -3 \end{bmatrix}$$

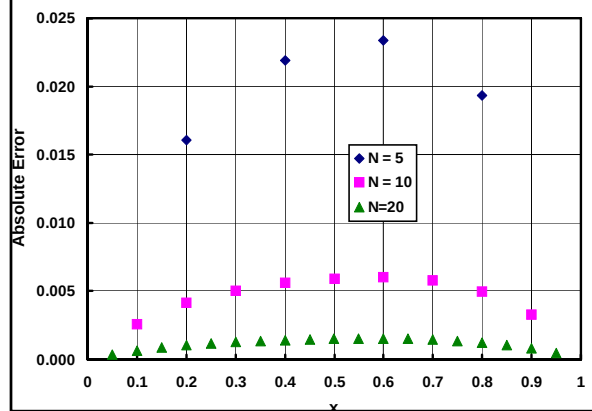
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43

Numerical and Exact Solution



Numerical Error



Error in Gradient

Exact dH/dx at $x = 0$ is -5.54268				
	Second order		First Order	
	dH/dx	Error	dH/dx	Error
N = 5	-5.0175	0.5252	-3.7719	1.7708
N = 10	-5.3713	0.1713	-4.6014	0.9413
N = 20	-5.5024	0.0403	-5.0648	0.4779
Exact dH/dx at $x = L$ is 8.98450				
	Second order		First Order	
	dH/dx	Error	dH/dx	Error
N = 5	8.1181	0.8664	6.3976	2.5869
N = 10	8.7104	0.2741	7.5899	1.3946
N = 20	8.9184	0.0661	8.2704	0.7141

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46