

220A Solutions

Assignment 15

14-4. The general description of a mass-spring system is

$$x = A \cos(\omega t + \phi) . \quad (1)$$

Note that eq 1 is one of a handful of equations that one needs to know by heart. Anything that oscillates according to simple harmonic motion follows the same equation. Of course,

$$v = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi) \quad (2)$$

All that is needed is to evaluate the constants, which we do by applying initial conditions as follows:

$$\text{at } t = 0, \quad x = 8.8 \text{ cm} = A \cos(\omega \cdot 0 + \phi) \quad (3)$$

and

$$v = 0 = -\omega(8.8 \text{ cm}) \sin(\omega \cdot 0 + \phi). \quad (4)$$

To get the angular frequency, ω , we need to use the information that $T = 0.75 \text{ s}$. Either look this up (middle of p. 366), or even better reason that when t increases from 0 to T , then the cosine returns to its original value so $\omega T = 2\pi$. Thus,

$$\omega = 2\pi/T = 2\pi/0.75 \text{ s} = 8.38 \text{ rad/s}. \quad (5)$$

Equations 2 and 3 become

$$8.8 \text{ cm} = A \cos(\phi) \quad (3')$$

and

$$0 = -8.38 \text{ rad/s} A (8.8 \text{ cm}) \sin(\phi). \quad (4')$$

We may solve the two equations 3' and 4' any way we want. An easy solution is to note that eq 4' requires that $\phi = 0$. Then, from 3', $A = 8.8 \text{ cm}$, and

$$x = 8.8 \text{ cm} \cos(8.38 \text{ rad/s} \cdot t), \quad (1)$$

from which we may calculate the position or the velocity (from the time derivative) at any time we wish. In particular, at $t = 1.8 \text{ s}$

$$x = 8.8 \text{ cm} \cdot \cos(8.38 \text{ rad/s} \cdot 1.8 \text{ s}) = -7.14 \text{ cm}$$

In this last computation, you have a choice of setting your calculator on "radians" or converting radians to degrees by multiplying the argument of the cosine by $\text{unity} = 180^\circ/\pi \text{ radians}$. I prefer the latter.

4-10. The frequency of a mass-spring system is given by

$$f = \sqrt{k/m} \quad (1)$$

Therefore,

$$0.88 \text{ Hz} = \sqrt{k/m} \quad (2)$$

and

$$0.48 \text{ Hz} = \sqrt{k/(m + 1.25 \text{ kg})} \quad (3)$$

Solve for m . One way to do this is to multiply eq 3 by $0.88/0.48$ and then set eq 2 = eq 3

$$\sqrt{k/m} = 0.88/0.48 \sqrt{k/(m + 1.25 \text{ kg})}, \text{ so}$$

$$k/m = (0.88/0.48)^2 k/(m + 1.25 \text{ kg}).$$

Canceling k leads to

$$m = (m + 1.25 \text{ kg})/(0.88/0.48)^2, \text{ so}$$

$$0.702 m = 0.372 \text{ kg}$$

$$m = 0.530 \text{ kg}.$$

14-13. Since $x = 3.8 \text{ m} \cos(7\pi t/4 + \pi/6)$ is a particular case of

$$x = A \cos(\omega t + \phi), \quad (1)$$

we can see that $\omega = 7\pi/4$ rad/s and $\phi = \pi/6$ rad. The period $T = 2\pi/\omega$, so

$T = 2\pi/(7\pi/4 \text{ rad/s}) = 1.14 \text{ s}$ and $f = 1/T = 0.875 \text{ Hz}$. The position at $t = 0$ is

$$x = 3.8\text{m} \cos(7\pi \cdot 0/4 + \pi/6) = 3.8\text{m} \cos(\pi/6) = 3.29 \text{ m}$$

The velocity $v = \frac{dx}{dt} = -(7\pi/4 \text{ rad/s}) (3.8 \text{ m})\sin(7\pi t/4 + \pi/6)$ which at $t = 0$ is

$$v = -(7\pi/4 \text{ rad/s}) (3.8 \text{ m})\sin(\pi/6) = -10.4 \text{ m/s},$$

and at $t = 2 \text{ s}$

$$v = -(7\pi/4 \text{ rad/s}) (3.8 \text{ m})\sin(7\pi \cdot 2\text{s}/4 + \pi/6) = 18.2 \text{ m/s}.$$

The acceleration $a = \frac{dv}{dt} = -(7\pi/4 \text{ rad/s})^2 (3.8 \text{ m})\cos(7\pi t/4 + \pi/6)$ which at $t = 2\text{s}$ is equal to

$$a = -(7\pi/4 \text{ rad/s})^2 (3.8 \text{ m})\cos(7\pi \cdot 2\text{s}/4 + \pi/6) = -57.4 \text{ m/s}^2.$$

14-14. The tuning fork moves according to

$$x = A \cos(\omega t + \phi). \quad (1)$$

with $\omega = 2\pi f = 2\pi \cdot 264 \text{ Hz} = 1659 \text{ rad/s}$ and $A = 1.5 \times 10^{-3} \text{ m}$. Since $v = \frac{dx}{dt} = -\omega A \sin(\omega t + \phi)$, the maximum value of v is when the sine is ± 1 so the maximum speed is $\omega A = 1659 \text{ rad/s} \cdot 1.5 \times 10^{-3} \text{ m} = 2.49 \text{ m/s}$. Similarly, taking another derivative, $a = -\omega^2 A \cos(\omega t + \phi)$, so the maximum value of a is $\omega^2 A = (1659 \text{ rad/s})^2 \cdot 1.5 \times 10^{-3} \text{ m} = 4.13 \times 10^3 \text{ m/s}^2$.

14-26. The total energy (kinetic + potential) of the SHO is

$$\begin{aligned} E &= \frac{1}{2} m v^2 + \frac{1}{2} k x^2 \\ &= \frac{1}{2} m (\omega A)^2 \sin^2(\omega t + \phi) + \frac{1}{2} k A^2 \cos^2(\omega t + \phi). \end{aligned}$$

Since $E = \text{constant}$, we can evaluate E anywhere, for example, when $x = A$; i.e., when $v = 0$. Thus $E = \frac{1}{2} kA^2$.

The potential energy is one-half E (and so is the kinetic energy) when

$$\frac{1}{2} kx^2 = \frac{1}{2} \cdot \frac{1}{2} kA^2,$$

$$x = \pm A/\sqrt{2}$$

When $x = A/2$, the potential energy $= \frac{1}{2} kx^2 = \frac{1}{2} kA^2/4 = E/4$. So the potential energy is 1/4 the total and thus the kinetic energy is 3/4.

14-27. The mass moves according to $x = 0.650 \text{ m} \cos(8.40 \text{ rad/s} \cdot t)$.

The amplitude is the maximum value of x which occurs when the cosine is unity, so $A = 0.650 \text{ m}$. The value of ω is 8.40 rad/s from which $f = \omega/2\pi = 1.34 \text{ Hz}$. The total energy $E = \frac{1}{2} m(\omega A)^2 = \frac{1}{2} 2 \text{ kg}(8.40 \text{ rad/s} \cdot 0.650 \text{ m})^2 = 29.8 \text{ J}$. The fraction of the total energy that is potential is $\frac{\frac{1}{2} kx^2}{\frac{1}{2} kA^2}$. At $x = 0.260 \text{ m}$, this fraction is $(0.260 \text{ m}/0.650 \text{ m})^2 = 0.16$. Thus the potential energy is $0.16 \cdot 29.8 \text{ J} = 4.77 \text{ J}$ and the kinetic energy is $0.84 \cdot 29.8 \text{ J} = 20.8 \text{ J}$.

14-68. To proceed, we must assume that energy is conserved (which is only approximate). Thus the potential energy of the jumper is mgh , where $h = 21.1 \text{ m}$ is the distance above the final position when the net is stretched. At this point the potential energy of the net is $\frac{1}{2} kx^2$ where $x = 1.1 \text{ m}$ is the amount stretched; x is positive downward. Thus

$$mgh = \frac{1}{2} kx^2$$

$$52 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 21.1 \text{ m} = \frac{1}{2} k(1.1 \text{ m})^2$$

from which we calculate $k = 1.79 \times 10^4 \text{ N/m}$. If the person were lying on the net, her weight mg would equal the upward force due to the net kx , where x is the amount stretched. Therefore,

$x = mg/k = 52 \text{ kg} \cdot 9.8 \text{ m/s}^2 / 1.79 \times 10^4 \text{ N/m} = 2.86 \times 10^{-2} \text{ m}$. If the person were to jump from 35 m, then $h = 35\text{m} + x$ and

$$mg(35\text{m} + x) = \frac{1}{2} kx^2$$

$$52 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot (35\text{m} + x) = \frac{1}{2} (1.79 \times 10^4 \text{ N/m}) x^2$$

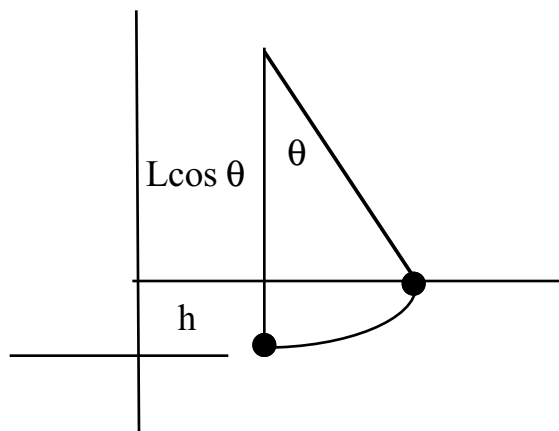
$$0 = 17.6 \text{ m}^{-1} \cdot x^2 - (35\text{m} + x) .$$

Thus

$$x = \frac{+1 \pm \sqrt{(-1)^2 - 4 \cdot 17.6 \text{ m}^{-1} \cdot (-35\text{m})}}{2 \cdot 17.6 \text{ m}^{-1}} = 2.84 \times 10^{-2} \text{ m} \pm 1.41 \text{ m}.$$

So $x = -1.38 \text{ m}$ or 1.44 m . Since x is positive downward, $x = 1.44 \text{ m}$. There is a reward of one ice-cream cone for anyone who can come tell me the meaning of the $x = -1.38 \text{ m}$ result.

14-69. The period of oscillation is approximately $T = 2\pi\sqrt{L/g} = 2\pi\sqrt{0.63 \text{ m}/9.8 \text{ m/s}^2} = 1.59 \text{ s}$, so $f = 1/T = 0.628 \text{ Hz}$. The total energy can be calculated at the highest point $E = mgh$ (since there is no kinetic energy), where h is the height above the lowest point. From the diagram, $L = h + L\cos\theta$, so $h = L[1 - \cos(15^\circ)] = 0.63 \text{ m} \cdot (3.41 \times 10^{-2}) = 2.14 \times 10^{-2} \text{ m}$.



The energy at the beginning mgh is equal to the energy when the bob passes the lowest point

$$mgh = \frac{1}{2} mv^2,$$

so

$$v = \pm \sqrt{2gh} = \pm 0.648 \text{ m/s.}$$

Evaluate E anywhere you want since it is constant. For example at the highest point, since the kinetic energy is zero,

$$E = mgh = 0.365 \text{ kg} \cdot 9.8 \text{ m/s}^2 \cdot 2.14 \times 10^{-2} \text{ m} = 7.65 \times 10^{-2} \text{ J.}$$