

Name: (print) _____

CSUN ID No. : Solutions

This test includes 7 questions (54 points in total) in the main part, and one bonus question worth an extra 6 points. Please check that your copy of the test has 8 pages. The duration of the test is 1 hour 15 minutes.

Your scores: (do not enter answers here)

1	2	3	4	5	6	7	8	total

Important: The test is closed books/notes. Graphing calculators are not permitted. Show all your work.

1. (6 points) Show based on the Replacement Theorem that if V is a vector space of dimension n then any linearly independent set in V that has exactly n vectors is a basis of V .

Let V be a vector space over F ,
 $\dim(V) = n$.

Let $S = \{v_1, \dots, v_n\}$ - linearly indep.

If S is not a basis then S is not generating,

$\exists w \in V, w \notin \text{span}\{S\}$

Then $\{w\} \cup S$ is a linearly indep.

set with $n+1$ elements,
 on contradiction to the Replacement
 Theorem.

2. (8 points) Let $V = \{(a_1, a_2) : a_1, a_2 \in \mathbb{R}\}$. For $(a_1, a_2), (b_1, b_2) \in V$ and $c \in \mathbb{R}$ define

$$(a_1, a_2) + (b_1, b_2) = (a_1 + b_1, a_2 + b_2)$$

$$c \cdot (a_1, a_2) = (ca_1, a_2/c) \quad \text{if } c \neq 0; \quad 0 \cdot (a_1, a_2) = (0, 0).$$

Is V a vector space over $\mathbb{R}$ with the operations '+' and '·'? Justify your answer.

No. If $c_1, c_2 \neq 0$,

$$(c_1 + c_2)(a_1, a_2) = ((c_1 + c_2)a_1, \frac{a_2}{c_1 + c_2})$$

$$\begin{aligned} c_1(a_1, a_2) + c_2(a_1, a_2) &= (c_1 a_1, \frac{a_2}{c_1}) + (c_2 a_1, \frac{a_2}{c_2}) \\ &= (c_1 a_1 + c_2 a_1, \frac{a_2}{c_1} + \frac{a_2}{c_2}) \\ &= ((c_1 + c_2)a_1, (\frac{1}{c_1} + \frac{1}{c_2})a_2) \end{aligned}$$

Take c_1, c_2 so that

$$\frac{1}{c_1 + c_2} \neq \frac{1}{c_1} + \frac{1}{c_2}, \quad \text{for instance } c_1 = 1, c_2 = 1$$

$\Rightarrow$ the distributive law is violated.

3. (6 points) The set of solutions of the linear system

$$\begin{cases} x_1 + x_2 - x_3 - x_4 = 0 \\ ix_1 + ix_2 - x_3 - x_4 = 0 \end{cases}$$

is a subspace of $\mathbb{C}^4$. Find a basis of this subspace.

Matrix form:

$$\begin{pmatrix} 1 & 1 & -1 & -1 & | & 0 \\ i & i & -1 & -1 & | & 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 1 & -1 & -1 & | & 0 \\ 0 & 0 & -1-i & -1-i & | & 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 1 & -1 & -1 & | & 0 \\ 0 & 0 & 1 & 1 & | & 0 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 1 & 1 & 0 & 0 & | & 0 \\ 0 & 0 & 1 & 1 & | & 0 \end{pmatrix}$$

Choose $x_2 = s$, $x_4 = t$ (free)

then

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = s \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \end{pmatrix}$$

The vectors are lin. indep (by 0-1 principle)

$$\Rightarrow \beta = \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ -1 \\ 1 \end{pmatrix} \right\} \text{ is a basis}$$

Continued...

4. (8 points) Let W be the subspace of $M_{2 \times 2}(\mathbb{C})$ consisting of all symmetric matrices. Construct an isomorphism from W to $\mathbb{C}^3$. Justify your answer.

$$W = \left\{ \begin{pmatrix} a & b \\ b & c \end{pmatrix} ; a, b, c \in \mathbb{C} \right\}$$

$$\text{Let } T: \begin{pmatrix} a & b \\ b & c \end{pmatrix} \mapsto \begin{pmatrix} a \\ b \\ c \end{pmatrix}.$$

Then T is linear (matrices are added component-by-component, and so are vectors in $\mathbb{C}^3$. Likewise for scalar multiplication)

The inverse of T is

$$T^{-1}: \begin{pmatrix} a \\ b \\ c \end{pmatrix} \mapsto \begin{pmatrix} a & b \\ b & c \end{pmatrix};$$

$$\text{then } T^{-1} \circ T = I_W;$$

$$T \circ T^{-1} = I_{\mathbb{C}^3}$$

$\Rightarrow T$ is invertible.

5. (8 points) Define $T : P_2(F) \rightarrow P_2(F)$ by $T(f(x)) = f(x) + f'(x)$.

(a) Find the matrix of the transformation T in the standard basis of $P_2(F)$: $\beta = (1, x, x^2)$.

$$T(1) = 1 ; \quad T(x) = x + 1 , \quad T(x^2) = x^2 + 2x$$

$$\Rightarrow [T]_{\beta}^{\beta} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\text{rank}([T]_{\beta}^{\beta}) = 3 \Rightarrow \text{nullity} = 0$$

$\Rightarrow$ there are no polynomials $f(x)$ besides zero that are transformed into zero by T

$$\Rightarrow N(T) = \{0\}.$$

$$\text{then } R(T) = P_2(F).$$

(b) Find bases of $R(T)$ and $N(T)$. [Hint: a basis of a vector space V is a subset of V .]

$$\text{basis of } R(T) : \{1, x, x^2\}$$

$$\text{basis of } N(T) : \emptyset.$$

6. (10 points) Formulate and prove the Rank-Nullity Theorem.

let V, W be vector spaces over F
and let $T: V \rightarrow W$ be linear.
If V is finite-dimensional, then
 $\dim(R(T)) + \dim(N(T)) = \dim(V)$.

Proof: Let $\beta_1 = \{u_1 \dots u_k\}$ be a basis of $N(T)$
($N(T)$ is finite-dim, since
it is a subspace of V)

Extend β_1 to $\beta = \{u_1 \dots u_k, u_{k+1}, \dots, u_n\}$ - basis of V .

Claim: $\beta_2 = \{T(u_{k+1}) \dots T(u_n)\}$ - basis of $R(T)$.

Indeed, if $y \in R(T)$ then $\exists x = a_1 u_1 + \dots + a_k u_k +$
 $a_{k+1} u_{k+1} + \dots + a_n u_n$

such that $y = T(x) = T(\underbrace{a_1 u_1 + \dots + a_k u_k}_{\in N(T)} + a_{k+1} u_{k+1} + \dots + a_n u_n)$

$$= a_{k+1} T(u_{k+1}) + \dots + a_n T(u_n)$$

$\Rightarrow \beta_2$ generates $R(T)$.

Check that β_2 is lin. indep.:

if $c_{k+1} T(u_{k+1}) + \dots + c_n T(u_n) = 0$

then $T(c_{k+1} u_{k+1} + \dots + c_n u_n) = 0$

$\Rightarrow c_{k+1} u_{k+1} + \dots + c_n u_n \in N(T)$

$\Rightarrow c_{k+1} u_{k+1} + \dots + c_n u_n = -c_1 u_1 - \dots - c_k u_k$

for certain $c_1, \dots, c_k$.

$\Rightarrow c_1 u_1 + c_2 u_2 + \dots + c_n u_n = 0$

$\Rightarrow$ all $c_i = 0$ since $\{u_1, \dots, u_n\}$ is a
basis of V .

Continued...

7. (8 points) State which of the following statements are true or false. (You do not need to show your work.)

Notations V and W are used for vector spaces over a field F . I_n is the identity matrix of size n .

- (a) The intersection of any finite number of subspaces in a vector space V is a subspace of V .
- (b) The empty set is a subspace of every vector space.
- (c) If $T, U : V \rightarrow W$ are both linear and agree on a basis of V , then $T = U$.
- (d) If $T, U : V \rightarrow W$ are both linear and $[T]_\beta^\gamma = [U]_\beta^\gamma$ for some bases β and γ , then $T = U$.
- (e) $T : V \rightarrow W$ is linear if $\forall x, y \in V, \forall a \in F \ T(x + ay) = T(x) + aT(y)$.
- (f) If $A \in M_{n \times n}(\mathbb{R})$ then $A^2 = I_n$ implies that $A = I_n$ or $A = -I_n$.
- (g) If $A \in M_{n \times n}(\mathbb{R})$ then $A^2 = 0$ (the zero matrix) implies that $A = 0$.
- (h) If $T : V \rightarrow W$ is linear and onto, then the image of any linearly independent set in V is linearly independent in W .

Answers:

- (a) T
- (b) F
- (c) T
- (d) T
- (e) T
- (f) F
- (g) F
- (h) F

The end.

8. (bonus: 6 points) Let

$$W_1 = \text{span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \right\}$$

Give an example of a subspace W_2 in F^4 such that $W_1 \oplus W_2 = F^4$.

$$\text{Let } W_2 = \text{span} \left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} \right\}.$$

$$\text{Then } W_1 \cap W_2 = \{0\}$$

$$\text{Since } k \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} = l \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} \Rightarrow k = l = 0$$

$$\text{and } k \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} =$$

$$\text{Also, if } \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} \in F^4, \text{ then}$$

$$\begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix} = \begin{pmatrix} b \\ b \\ d \\ d \end{pmatrix} + \begin{pmatrix} a-b \\ 0 \\ c-d \\ 0 \end{pmatrix}$$

$$= b \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix} + d \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} + (a-b) \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} +$$

$$+ (c-d) \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}.$$

The end.