

## Additional Topics in Numerical Solutions of Parabolic Equations

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## Outline

- Complete discussion from last class
  - Fully implicit and DuFort-Frankel methods
- Review numerical diffusion solutions
  - Explicit and Crank-Nicholson methods
  - Thomas algorithm
- General properties of numerical algorithms for PDEs
- Numerical diffusion equation solutions in two or more space dimensions

## Fully Implicit Method

- Discretize diffusion equation at  $t_{n+1}$

$$\frac{\partial u}{\partial t} \Big|_i^{n+1} = \frac{u_i^{n+1} - u_i^n}{\Delta t} + O(\Delta t) \quad \text{and} \quad \frac{\partial^2 u}{\partial x^2} \Big|_i^{n+1} = \frac{u_{i+1}^{n+1} + u_{i-1}^{n+1} - 2u_i^{n+1}}{(\Delta x)^2} + O[(\Delta x)^2]$$

$$\frac{\partial u}{\partial t} \Big|_i^{n+1} - \alpha \frac{\partial^2 u}{\partial x^2} \Big|_i^{n+1} = \frac{u_i^{n+1} - u_i^n}{\Delta t} - \alpha \frac{u_{i+1}^{n+1} + u_{i-1}^{n+1} - 2u_i^{n+1}}{(\Delta x)^2} + O[(\Delta t), (\Delta x)^2] = 0$$

$$-fu_{i-1}^{n+1} + (1+2f)u_i^{n+1} - fu_{i+1}^{n+1} = u_i^n$$

- Tridiagonal system of equations
- Almost same work as CN and no spurious oscillations, but less accuracy

## Fully Implicit (BTCS) Results

- Same as CN inputs:  $\alpha = 1, L = 1, \Delta x = 0.01, \Delta t = 0.0005, f = \alpha\Delta t/(\Delta x)^2 = 5$

|       |            | i = 0 | i = 1   | i = 2   | i = 3   | i = 4   |
|-------|------------|-------|---------|---------|---------|---------|
|       |            | x = 0 | x = .01 | x = .02 | x = .03 | x = .04 |
|       | t = 0      | 1000  | 1000    | 1000    | 1000    | 1000    |
| n = 0 | t = 0+     | 0     | 1000    | 1000    | 1000    | 1000    |
| n = 1 | t = 0.0005 | 0     | 358.26  | 588.17  | 735.71  | 830.39  |
| n = 2 | t = 0.001  | 0     | 218.22  | 408.43  | 562.69  | 682.35  |
| n = 3 | t = 0.0015 | 0     | 166.26  | 322.13  | 460.74  | 578.96  |
| n = 4 | t = 0.002  | 0     | 139.05  | 272.65  | 396.35  | 507.18  |
| n = 5 | t = 0.0025 | 0     | 121.84  | 240.25  | 352.17  | 455.26  |
| n = 6 | t = 0.003  | 0     | 109.75  | 217.08  | 319.77  | 415.99  |

## Fully Implicit Results II

|        |            | i = 0 | i = 1   | i = 2   | i = 3   | i = 4   |
|--------|------------|-------|---------|---------|---------|---------|
|        |            | x = 0 | x = .01 | x = .02 | x = .03 | x = .04 |
| n = 7  | t = 0.0035 | 0     | 100.65  | 199.49  | 294.81  | 385.13  |
| n = 8  | t = 0.004  | 0     | 93.50   | 185.57  | 274.85  | 360.14  |
| n = 9  | t = 0.0045 | 0     | 87.68   | 174.19  | 258.43  | 339.38  |
| n = 10 | t = 0.005  | 0     | 82.82   | 164.67  | 244.62  | 321.81  |
| n = 11 | t = 0.0055 | 0     | 78.69   | 156.56  | 232.81  | 306.69  |
| n = 12 | t = 0.006  | 0     | 75.13   | 149.54  | 222.55  | 293.50  |
| n = 13 | t = 0.0065 | 0     | 72.00   | 143.38  | 213.53  | 281.87  |
| n = 14 | t = 0.007  | 0     | 69.24   | 137.93  | 205.52  | 271.52  |
| n = 15 | t = 0.0075 | 0     | 66.77   | 133.05  | 198.35  | 262.22  |
| n = 16 | t = 0.008  | 0     | 64.55   | 128.66  | 191.88  | 253.82  |
| n = 17 | t = 0.0085 | 0     | 62.54   | 124.67  | 186.01  | 246.17  |

## Fully Implicit Results III

|        |            | i = 0 | i = 1   | i = 2   | i = 3   | i = 4   |
|--------|------------|-------|---------|---------|---------|---------|
|        |            | x = 0 | x = .01 | x = .02 | x = .03 | x = .04 |
| n = 18 | t = 0.009  | 0     | 60.70   | 121.03  | 180.64  | 239.17  |
| n = 19 | t = 0.0095 | 0     | 59.02   | 117.70  | 175.71  | 232.74  |
| n = 20 | t = 0.01   | 0     | 57.47   | 114.62  | 171.16  | 226.79  |
| n = 21 | t = 0.0105 | 0     | 56.03   | 111.78  | 166.95  | 221.28  |
| n = 22 | t = 0.011  | 0     | 54.70   | 109.13  | 163.04  | 216.16  |
| n = 23 | t = 0.0115 | 0     | 53.46   | 106.67  | 159.38  | 211.37  |
| n = 24 | t = 0.012  | 0     | 52.30   | 104.36  | 155.96  | 206.88  |
| n = 25 | t = 0.0125 | 0     | 51.21   | 102.20  | 152.76  | 202.67  |
| Exact  | t = 0.0125 | 0     | 50.43   | 100.66  | 150.48  | 199.72  |
| Error  | t = 0.0125 | 0     | 0.779   | 1.542   | 2.273   | 2.956   |

### Compare Crank Nicholson

|        |            | i = 0 | i = 1   | i = 2   | i = 3   | i = 4   |
|--------|------------|-------|---------|---------|---------|---------|
|        |            | x = 0 | x = .01 | x = .02 | x = .03 | x = .04 |
| n = 18 | t = 0.009  | 0     | 60.65   | 117     | 177.71  | 234.21  |
| n = 19 | t = 0.0095 | 0     | 56.86   | 116.5   | 171.59  | 228.43  |
| n = 20 | t = 0.01   | 0     | 57.1    | 111.53  | 168.52  | 222.53  |
| n = 21 | t = 0.0105 | 0     | 54.43   | 110.47  | 163.53  | 217.57  |
| n = 22 | t = 0.011  | 0     | 54.19   | 106.68  | 160.64  | 212.45  |
| n = 23 | t = 0.0115 | 0     | 52.22   | 105.35  | 156.49  | 208.11  |
| n = 24 | t = 0.012  | 0     | 51.73   | 102.36  | 153.78  | 203.64  |
| n = 25 | t = 0.0125 | 0     | 50.21   | 100.93  | 150.27  | 199.78  |
| Exact  | t = 0.0125 | 0     | 50.43   | 100.66  | 150.48  | 199.72  |
| Error  | t = 0.0125 | 0     | 0.216   | 0.272   | 0.212   | 0.061   |

### Richardson/Leapfrog

- Use two time step central differences

$$\frac{\partial u}{\partial t} \Big|_i^n = \frac{u_i^{n+1} - u_i^{n-1}}{2\Delta t} + O[(\Delta t)^2] = \alpha \frac{\partial^2 u}{\partial x^2} \Big|_i^n = \alpha \frac{u_{i+1}^n + u_{i-1}^n - 2u_i^n}{(\Delta x)^2} + O[(\Delta x)^2]$$

- Result is explicit with second order accuracy in time

$$u_i^{n+1} = u_i^{n-1} + \frac{2\alpha\Delta t}{(\Delta x)^2} (u_{i+1}^n + u_{i-1}^n - 2u_i^n) = u_i^{n-1} + 2f(u_{i+1}^n + u_{i-1}^n - 2u_i^n)$$

- However result is unstable for any f and cannot be used

### DuFort Frankel

- Modification of Richardson method to provide stability
- Replace  $2u_i^n$  in second derivative by average at time steps n+1 and n-1
- Introduces another  $O[(\Delta t)^2]$  error

$$\frac{\partial u}{\partial t} \Big|_i^n = \frac{u_i^{n+1} - u_i^{n-1}}{2\Delta t} + O[(\Delta t)^2] = \alpha \frac{\partial^2 u}{\partial x^2} \Big|_i^n = \alpha \frac{u_{i+1}^n + u_{i-1}^n - 2u_i^n}{(\Delta x)^2} + O[(\Delta x)^2]$$

$$2u_i^n = u_i^{n+1} + u_i^{n-1} + O[(\Delta t)^2]$$

$$\frac{u_i^{n+1} - u_i^{n-1}}{2\Delta t} = \alpha \frac{u_{i+1}^n + u_{i-1}^n - \frac{u_i^{n+1} + u_i^{n-1}}{2}}{(\Delta x)^2} + O[(\Delta x)^2, (\Delta t)^2, \frac{(\Delta t)^2}{(\Delta x)^2}]$$

### DuFort Frankel

- Rearrange and introduce  $f = \alpha\Delta t/(\Delta x)^2$

$$u_i^{n+1} - u_i^{n-1} = \frac{2\alpha\Delta t}{(\Delta x)^2} (u_{i+1}^n + u_{i-1}^n - u_i^{n+1} - u_i^{n-1}) = 2f(u_{i+1}^n + u_{i-1}^n - u_i^{n+1} - u_i^{n-1})$$

$$(1 + 2f)u_i^{n+1} = u_i^{n-1}(1 - 2f) + 2f(u_{i+1}^n + u_{i-1}^n)$$

- Result is explicit for values at time n+1
- Explicit start required to get first set of values at time n-1
- Can show that this is unconditionally stable

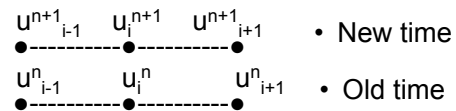
### Truncation Error

- Truncation error for DuFort-Frankel
  - Derivation in appendix to notes on numerical solutions for PDEs
- Set  $f^2 = 1/12$  ( $f = 0.288675\dots$ ) for minimum truncation error

$$TE = \left( \frac{1}{12f} - f \right) \frac{\partial^2 T}{\partial t^2} \Big|_i^n \Delta t - \sum_{k=1}^{\infty} \frac{(\Delta t)^{2k}}{(2k+1)!} \frac{\partial^{2k+1} T}{\partial t^{2k+1}} \Big|_i^n$$

$$- 2f \sum_{k=2}^{\infty} \frac{(\Delta t)^{2k-1}}{(2k)!} \frac{\partial^{2k} T}{\partial t^{2k}} \Big|_i^n + 2 \sum_{k=3}^{\infty} \frac{(\Delta t)^{k-1}}{f^{k-1} (2k)!} \frac{\partial^k T}{\partial t^k} \Big|_i^n$$

### Review Diffusion Algorithms



- Explicit  $u_i^{n+1} = f(u_{i+1}^n + u_{i-1}^n) + (1 - 2f)u_i^n$
- Fully implicit  $-fu_{i-1}^{n+1} + (1 + 2f)u_i^{n+1} - fu_{i+1}^{n+1} = u_i^n$
- Crank-Nicholson  $-fu_{i-1}^{n+1} + 2(1 + f)u_i^{n+1} - fu_{i+1}^{n+1} = f[u_{i+1}^n + u_{i-1}^n] + 2(1 - f)u_i^n = R_i$
- DuFort-Frankel  $(1 + 2f)u_i^{n+1} = u_i^{n-1}(1 - 2f) + 2f(u_{i+1}^n + u_{i-1}^n)$

### Review Implicit Equations

- Crank Nicholson  $-fu_{i-1}^{n+1} + 2(1+f)u_i^{n+1} - fu_{i+1}^{n+1} =$  and fully implicit  $f[u_{i+1}^{n+1} + u_{i-1}^n] + 2(1-f)u_i^n = R_i$  have three values at new time step  $-fu_{i-1}^{n+1} + (1+2f)u_i^{n+1} - fu_{i+1}^{n+1} = u_i^n$
- Tridiagonal system of equations easily solved by special application of Gauss elimination called Thomas algorithm
  - General tridiagonal form is

$$A_i u_{i-1}^{n+1} + B_i u_i^{n+1} + C_i u_{i+1}^{n+1} = D_i$$

### Review Thomas Algorithm

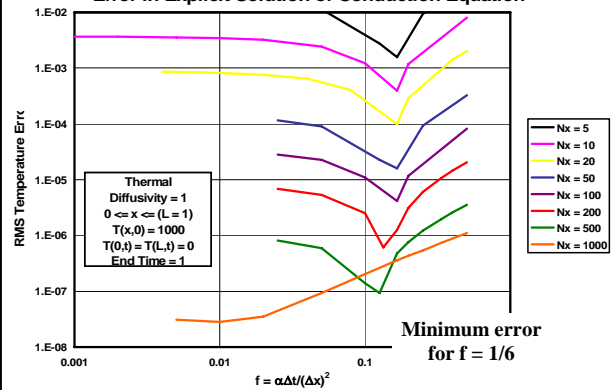
- Solution procedure for tridiagonal equations  $A_i x_{i-1} + B_i x_i + C_i x_{i+1} = D_i$
- Special application of conventional Gaussian elimination
- Equations for  $E_i$  and  $F_i$ ,  $i = 0, N$
- Get  $x_N = F_N$
- Get  $x_i = F_i + E_i x_{i+1}$  for  $i = N - 1$  to 1

$$\begin{bmatrix} B_0 & C_0 & 0 & 0 & \dots & 0 & 0 \\ A_1 & B_1 & C_1 & 0 & \dots & 0 & 0 \\ 0 & A_2 & B_2 & C_2 & \dots & 0 & 0 \\ 0 & 0 & A_3 & B_3 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & B_{N-1} & C_{N-1} \\ 0 & 0 & 0 & 0 & \dots & A_N & B_N \end{bmatrix} \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ \vdots \\ x_{N-1} \\ x_N \end{bmatrix} = \begin{bmatrix} D_0 \\ D_1 \\ D_2 \\ \vdots \\ D_{N-1} \\ D_N \end{bmatrix}$$

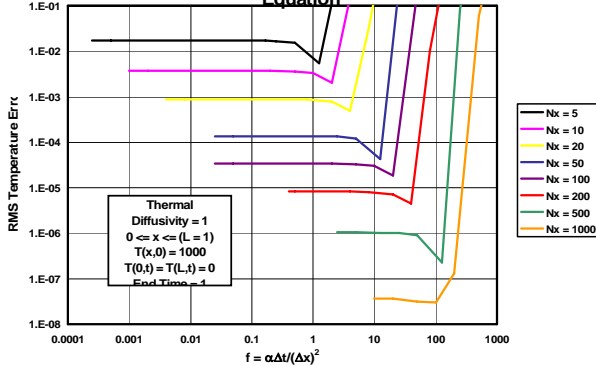
### Review Stability Limits

- Saw unexpected oscillations when time step is too large
  - Stable algorithm: oscillations damp out
  - Unstable: oscillations grow without bound
  - Conditional stability: limit on time step
  - Explicit method requires  $f = \alpha \Delta t / (\Delta x)^2 < 1/2$
- Fully implicit, Crank-Nicholson, and DuFort-Frankel are unconditionally stable
  - Have large errors with  $\Delta t$  too large
  - Keep  $f$  about 1

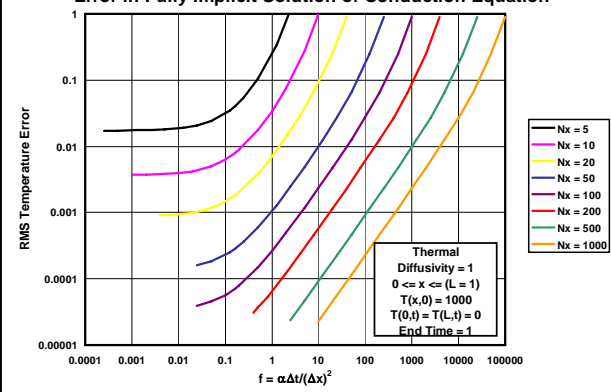
Error in Explicit Solution of Conduction Equation

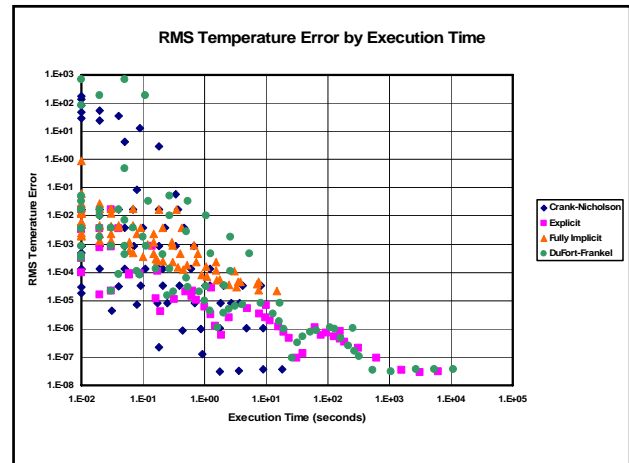
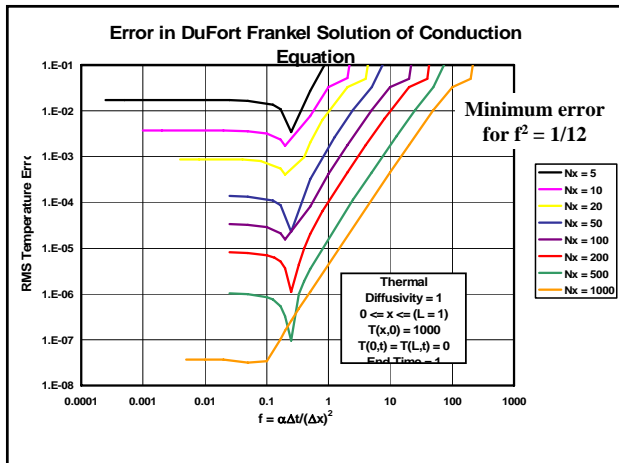


Error in Crank-Nicholson Solution of Conduction Equation



Error in Fully Implicit Solution of Conduction Equation





### Properties of Solutions

- *Consistency* – truncation error becomes zero as step sizes approach zero
- *Stability* – errors remain bounded
- *Convergent* – tends to the exact solution of the differential equation as the grid size tends towards zero
- *Physical reality* – Solutions produce physically realistic results
- *Accuracy* – Many sources of error in numerical solutions.

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### Consistency

- Write finite difference expression
- Then write Taylor series for each algebraic term in finite difference expression
- Result will be an equation with derivatives and  $\Delta x, \Delta y, \Delta z, \Delta t$ , etc.
- If we let  $\Delta x, \Delta y, \Delta z, \Delta t$ , etc. approach zero are we left with the differential equation that we are trying to solve?

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### Stability

- Solution of difference equations with finite steps gives different results
  - Absolute stability: solution remains bounded for any choice of step size
  - Conditional stability: solution remains bounded for limited step sizes
  - Unconditional instability: Solution is not bounded for any choice of step size
  - Prefer absolute stability but can work with conditional stability

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### Convergence

- An algorithm that is consistent and stable is convergent (Lax's theorem)
- Not usually a practical concern to a user of algorithms
- Can run a code with different step sizes and see that solution approaches a consistent value as step size decreases
- DuFort Frankel is neither consistent nor convergent, but gives good results for some choices of  $\Delta x$  and  $\Delta t$

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### Physical Reality

- Solutions to diffusion equation show uniform decreases – Crank-Nicholson, a stable and convergent algorithm can give oscillations
- Solutions to the wave equation should have no dissipation (an original wave form should propagate with no change in shape) – some algorithms may not give this result

### Problems with Accuracy

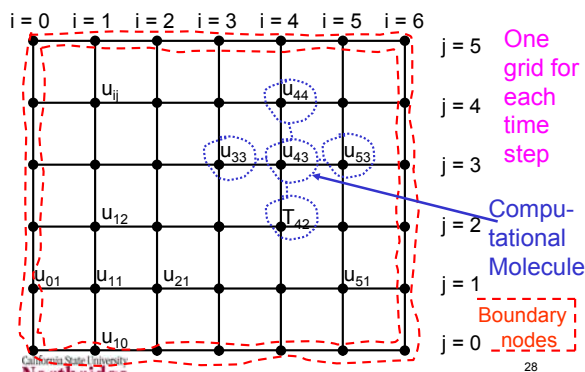
- Truncation and round-off errors
- Iterative solution of algebraic equations
- Poor physical models or assumptions
- Blunders
  - Programming errors
  - Incorrect data entries
  - Misinterpretation of results
  - Belief that pretty output must be correct

### Two Space Dimensions

- Extension of one space dimension
- Have grid in  $y_j$  as well as  $x_i$  and time
- Explicit method has almost no difference
- Implicit methods harder to solve
- Differential equation shown below
- Explicit method uses same time and space derivatives as in one space dimension

$$\left[ \frac{\partial u}{\partial t} = \alpha \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \right]_{ij}^n$$

### A Small Grid (N = 6, M = 5)



### Two Space Dimensions II

- Explicit method has error that is second order in space and first order in time

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} = \alpha \frac{u_{i+1j}^n + u_{i-1j}^n - 2u_{ij}^n}{(\Delta x)^2} + \alpha \frac{u_{ij+1}^n + u_{ij-1}^n - 2u_{ij}^n}{(\Delta y)^2}$$

$$f_x \equiv \frac{\alpha \Delta t}{(\Delta x)^2} \quad f_y \equiv \frac{\alpha \Delta t}{(\Delta y)^2}$$

$$u_{ij}^{n+1} = f_x (u_{i+1j}^n + u_{i-1j}^n) + f_y (u_{ij+1}^n + u_{ij-1}^n) + (1 - 2f_x - 2f_y) u_{ij}^n$$

### Two Space Dimensions III

- If  $\Delta x = \Delta y = h$  so that  $f_x = f_y = f$ , the explicit equation becomes

$$u_{ij}^{n+1} = f(u_{i+1j}^n + u_{i-1j}^n) + f(u_{ij+1}^n + u_{ij-1}^n) + (1 - 4f)u_{ij}^n$$

- $1 - 4f$  must be positive for stability

$$f = f_x = \frac{\alpha \Delta t}{(\Delta x)^2} = f_y = \frac{\alpha \Delta t}{(\Delta y)^2} \leq \frac{1}{4}$$

- In general  $1 - 2f_x - 2f_y$  must be positive

$$f_x + f_y = \frac{\alpha \Delta t}{(\Delta x)^2} + \frac{\alpha \Delta t}{(\Delta y)^2} \leq \frac{1}{2}$$

### CN in Two Space Dimensions

- One-dimensional finite-difference equation

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} = \frac{\alpha}{2} \left[ \frac{u_{i+1j}^{n+1} + u_{i-1j}^{n+1} - 2u_{ij}^{n+1}}{(\Delta x)^2} + \frac{u_{i+1j}^n + u_{i-1j}^n - 2u_{ij}^n}{(\Delta x)^2} \right]$$

- Extend this to two dimensions

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} = \frac{\alpha}{2} \left[ \frac{u_{i+1j}^{n+1} + u_{i-1j}^{n+1} - 2u_{ij}^{n+1}}{(\Delta x)^2} + \frac{u_{i+1j}^n + u_{i-1j}^n - 2u_{ij}^n}{(\Delta x)^2} + \frac{u_{ij+1}^{n+1} + u_{ij-1}^{n+1} - 2u_{ij}^{n+1}}{(\Delta y)^2} + \frac{u_{ij+1}^n + u_{ij-1}^n - 2u_{ij}^n}{(\Delta y)^2} \right]$$

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### CN in Two Space Dimensions II

- Substitute  $f_x = \alpha\Delta t/(\Delta x)^2$  and  $f_y = \alpha\Delta t/(\Delta y)^2$

$$T_{ij}^{n+1} - T_{ij}^n = \frac{f_x}{2} [u_{i+1j}^{n+1} + u_{i-1j}^{n+1} - 2u_{ij}^{n+1} + u_{i+1j}^n + u_{i-1j}^n - 2u_{ij}^n] + \frac{f_y}{2} [u_{ij+1}^{n+1} + u_{ij-1}^{n+1} - 2u_{ij}^{n+1} + u_{ij+1}^n + u_{ij-1}^n - 2u_{ij}^n]$$

- Multiply by 2 and rearrange to obtain

$$-f_y u_{ij+1}^{n+1} - f_x u_{i+1j}^{n+1} + 2(1 + f_x + f_y) u_{ij}^{n+1} - f_x u_{i-1j}^{n+1} - f_y u_{ij-1}^{n+1} = f_x (u_{i+1j}^n + u_{i-1j}^n) + f_y (u_{ij+1}^n + u_{ij-1}^n) + 2(1 - f_x - f_y) u_{ij}^n = R_{ij}^n$$

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### FI in Two Space Dimensions

- One-dimensional fully implicit  $-f u_{i-1}^{n+1} + (1 + 2f) u_i^{n+1} - f u_{i+1}^{n+1} = u_i^n$
- Extend this to two dimensions

$$-f_y u_{ij-1}^{n+1} - f_x u_{i-1j}^{n+1} + (1 + 2f_x + 2f_y) u_{ij}^{n+1} - f_x u_{i+1j}^{n+1} - f_y u_{ij+1}^{n+1} = u_{ij}^n$$

- System of implicit equations is not tridiagonal
- Look at small grid
- Keep same grid for all time steps
  - Have to store one time step only

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### Finite-difference Grid

- Node related to four nearest neighbors at both time steps
- CN uses all potential values at old time step
- Discuss iteration methods with Laplace equation

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### A Small Grid (N = 6, M = 5)

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### Alternating Direction Implicit

- ADI is technique for allowing use of Thomas algorithm for simple solution
  - At each time step, treat one direction as explicit and one as implicit
  - Exchange explicit and implicit directions at each time step
  - Keep results at each time step, but always have an even number of time steps
- Different approaches include Peaceman-Radford and Douglas-Radford

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### Peaceman-Radford ADI

- Solve first for approximate  $u^*$  at  $t_{n+1}$

$$\frac{u_{ij}^* - u_{ij}^n}{\Delta t} = \alpha \left[ \frac{u_{i+1j}^* + u_{i-1j}^* - 2u_{ij}^*}{(\Delta x)^2} + \frac{u_{ij+1}^n + u_{ij-1}^n - 2u_{ij}^n}{(\Delta y)^2} \right]$$

- Solve next for actual result  $u^{n+2}$

$$\frac{u_{ij}^{n+2} - u_{ij}^*}{\Delta t} = \alpha \left[ \frac{u_{i+1j}^* + u_{i-1j}^* - 2u_{ij}^*}{(\Delta x)^2} + \frac{u_{ij+1}^{n+2} + u_{ij-1}^{n+2} - 2u_{ij}^{n+2}}{(\Delta y)^2} \right]$$

- Each equation gives a tridiagonal system

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### Peaceman Radford II

- Introduce  $f_x = \alpha \Delta t / (\Delta x)^2$  and  $f_y = \alpha \Delta t / (\Delta y)^2$  and get tridiagonal forms
- First time step

$$-f_x u_{i-1j}^* + (1 + 2f_x) u_{ij}^* - f_x u_{i+1j}^* = f_y (u_{ij+1}^n + u_{ij-1}^n) + (1 - 2f_y) u_{ij}^n$$

$$-f_x u_{i-1j}^* + (1 + 2f_x) u_{ij}^* - f_x u_{i+1j}^* = R_{ij}^n$$

- Second time step

$$-f_y u_{ij-1}^{n+2} + (1 + 2f_y) u_{ij}^{n+2} - f_y u_{ij+1}^{n+2} = f_x (u_{i+1j}^* + u_{i-1j}^*) + (1 - 2f_x) u_{ij}^*$$

$$-f_y u_{ij-1}^{n+2} + (1 + 2f_y) u_{ij}^{n+2} - f_y u_{ij+1}^{n+2} = R_{ij}^{n+1}$$

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### Three Dimensional Problem

- Extend explicit two-dimensional finite-difference form to three-dimensions

$$\frac{u_{ijk}^{n+1} - u_{ijk}^n}{\Delta t} = \alpha \frac{u_{i+1jk}^n + u_{i-1jk}^n - 2u_{ijk}^n}{(\Delta x)^2} + \alpha \frac{u_{ij+1k}^n + u_{ij-1k}^n - 2u_{ijk}^n}{(\Delta y)^2} + \alpha \frac{u_{ijk+1}^n + u_{ijk-1}^n - 2u_{ijk}^n}{(\Delta z)^2}$$

$$f_x = \frac{\alpha \Delta t}{(\Delta x)^2} \quad f_y = \frac{\alpha \Delta t}{(\Delta y)^2} \quad f_z = \frac{\alpha \Delta t}{(\Delta z)^2}$$

$$f_x + f_y + f_z \leq \frac{1}{2}$$

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### Douglas-Brian Method

- An ADI method in three steps

$$\frac{u_{ijk}^* - u_{ijk}^n}{\Delta t} = \frac{\alpha}{2} \left[ \frac{u_{i+1jk}^* + u_{i-1jk}^* - 2u_{ijk}^*}{(\Delta x)^2} + \frac{u_{i+1jk}^n + u_{i-1jk}^n - 2u_{ijk}^n}{(\Delta x)^2} \right]$$

$$\alpha \frac{u_{ij+1k}^n + u_{ij-1k}^n - 2u_{ijk}^n}{(\Delta y)^2} + \alpha \frac{u_{ijk+1}^n + u_{ijk-1}^n - 2u_{ijk}^n}{(\Delta z)^2}$$

$$\frac{u_{ijk}^{**} - u_{ijk}^*}{\Delta t} = \frac{\alpha}{2} \left[ \frac{u_{i+1jk}^* + u_{i-1jk}^* - 2u_{ijk}^*}{(\Delta x)^2} + \frac{u_{i+1jk}^n + u_{i-1jk}^n - 2u_{ijk}^n}{(\Delta x)^2} \right] + \alpha \left[ \frac{u_{ij+1k}^{**} + u_{ij-1k}^{**} - 2u_{ijk}^{**}}{(\Delta y)^2} + \frac{u_{ij+1k}^n + u_{ij-1k}^n - 2u_{ijk}^n}{(\Delta y)^2} \right] + \alpha \frac{u_{ijk+1}^n + u_{ijk-1}^n - 2u_{ijk}^n}{(\Delta z)^2}$$

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### Douglas-Brian Method II

$$\frac{u_{ijk}^{n+1} - u_{ijk}^n}{\Delta t} = \frac{\alpha}{2} \left[ \frac{u_{i+1jk}^* + u_{i-1jk}^* - 2u_{ijk}^*}{(\Delta x)^2} + \frac{u_{i+1jk}^n + u_{i-1jk}^n - 2u_{ijk}^n}{(\Delta x)^2} \right]$$

$$+ \frac{\alpha}{2} \left[ \frac{u_{ij+1k}^{**} + u_{ij-1k}^{**} - 2u_{ijk}^{**}}{(\Delta y)^2} + \frac{u_{ij+1k}^n + u_{ij-1k}^n - 2u_{ijk}^n}{(\Delta y)^2} \right]$$

$$+ \frac{\alpha}{2} \left[ \frac{u_{ijk+1}^{n+1} + u_{ijk-1}^{n+1} - 2u_{ijk}^{n+1}}{(\Delta z)^2} + \frac{u_{ijk+1}^n + u_{ijk-1}^n - 2u_{ijk}^n}{(\Delta z)^2} \right]$$

- Each step – solving for  $u^*$ ,  $u^{**}$ , and  $u^{n+1}$ , has a tridiagonal system of equations
  - Can show that this is unconditionally stable with  $O[(\Delta t)^2, (\Delta x)^2, (\Delta y)^2, (\Delta z)^2]$  truncation error

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### Operator Splitting

- A method similar to ADI
- Allows use of Thomas algorithm to solve a tridiagonal system of equations
- Uses difference operator notation,  $\Delta_x^2 \phi_{ij} = \phi_{i+1j} + \phi_{i-1j} - 2\phi_{ij}$  and  $\Delta_y^2 \phi_{ij} = \phi_{ij+1} + \phi_{ij-1} - 2\phi_{ij}$
- Uses two operator factors and ignores cross product which produces same error as time derivative,  $O[(\Delta t)^2]$

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### Operator Splitting

- Like ADI, but do not use midpoint step
- Here use difference operator notation,  $\Delta^2$

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} = \alpha \left[ \frac{u_{i+1j}^{n+1} + u_{i-1j}^{n+1} - 2u_{ij}^{n+1}}{(\Delta x)^2} + \frac{u_{ij+1}^{n+1} + u_{ij-1}^{n+1} - 2u_{ij}^{n+1}}{(\Delta y)^2} \right]$$

$$\frac{u_{ij}^{n+1} - u_{ij}^n}{\Delta t} = \alpha \left[ \frac{\Delta_x^2}{(\Delta x)^2} + \frac{\Delta_y^2}{(\Delta y)^2} \right] u_{ij}^{n+1}$$

$$\left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right) u_{ij}^{n+1} = u_{ij}^n$$

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### Operator Splitting II

- Use approximate factorization

$$\left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right) u_{ij}^{n+1} = \left[ 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} \right] \left[ 1 - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right] u_{ij}^{n+1} - (\alpha \Delta t)^2 \frac{\Delta_x^2}{(\Delta x)^2} \frac{\Delta_y^2}{(\Delta y)^2} u_{ij}^{n+1} = u_{ij}^n$$

Ignoring this term gives  $O[(\Delta t)^2]$  error

- Result with  $O[(\Delta t)^2]$  term neglected

$$\left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} \right) \left( 1 - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right) u_{ij}^{n+1} = u_{ij}^n$$

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### Operator Splitting III

- Define intermediate value  $u_{ij}^*$

$$\left( 1 - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right) \left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} \right) u_{ij}^{n+1} = u_{ij}^n$$

$$\left( 1 - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right) u_{ij}^* = \left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} \right) \left[ \left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} \right) u_{ij}^{n+1} \right] = u_{ij}^n$$

- Solve two sets of tridiagonal equations for each time step

$$\left( 1 - \alpha \Delta t \frac{\Delta_y^2}{(\Delta y)^2} \right) u_{ij}^* = u_{ij}^n$$

$$\left( 1 - \alpha \Delta t \frac{\Delta_x^2}{(\Delta x)^2} \right) u_{ij}^{n+1} = u_{ij}^*$$

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