

## December 6 Homework Problems

1. Use the Euler method,  $\mathbf{y}_{n+1} = \mathbf{y}_n + hf(x_n, \mathbf{y}_n)$ , for a system of equations to solve  $y_1' = 2y_1 - 4y_2$ ,  $y_2' = y_1 - 3y_2$ ,  $y_1(0) = 3$ ,  $y_2(0) = 0$ . Solve for ten steps with  $h = 0.1$  and plot the solution in the  $y_1$ - $y_2$  plane.
2. Use the fourth-order Runge-Kutta method for the system of equations solved in problem 1:  $y_1' = 2y_1 - 4y_2$ ,  $y_2' = y_1 - 3y_2$ ,  $y_1(0) = 3$ ,  $y_2(0) = 0$ . Solve for two steps with  $h = 0.5$  and compare the results to those in problem 1.
3. Consider the model stiff ODE:  $y' = -1000[y - (t + 2)] + 1$ ,  $y(0) = 1$ . Solve this ODE by the explicit Euler method from  $t = 0$  to  $t = 0.01$  using  $h = 0.0005$ ,  $0.0001$ ,  $0.002$ , and  $0.0025$ . Compare the solution with the exact solution:  $y = -e^{-1000t} + t + 2$
4. Solve  $y' = -1000[y - (t + 2)] + 1$ ,  $y(0) = 1$  by the second-order Gear method from  $t = 0$  to  $t = 0.1$  using  $h = 0.01$ , and  $0.02$ . The equation for the second-order Gear method is

$$y_{n+1} = \frac{2}{3}hf_{n+1} + \frac{4}{3}y_n - \frac{1}{3}y_{n-1}$$

Note that for this textbook problem you can write an equation for  $f_{n+1}$  and substitute it into the Gear algorithm to obtain an equation that is linear in  $y_{n+1}$ . You can solve that equation for  $y_{n+1}$  so that you will not have to iterate each step of the solution. Use the exact solution,  $y = -e^{-1000t} + t + 2$ , to get the necessary starting values.

5. Solve the following ODE  $y'' + (1+x)y' + (1+x)y = 1$  with  $y(0) = 1$  and  $y'(1) = 0$ , by the shooting (shoot-and-try) method using the second-order modified Euler method, given by the equations below, with  $h = 0.125$ .

$$y_{n+1}^P = y_n + hf(x_n, y_n) \quad y_{n+1}^C = y_n + \frac{h}{2} [f(x_n, y_n) + f(x_{n+1}, y_{n+1}^P)]$$