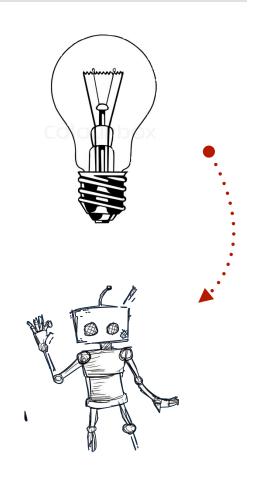
BEHAVIOR ANALYSTS THINK; CAN ROBOTS DO? USING HUMAN ANALOGUES IN TRANSLATIONAL RESEARCH

MELINE POGOSJANA & ELLIE KAZEMI

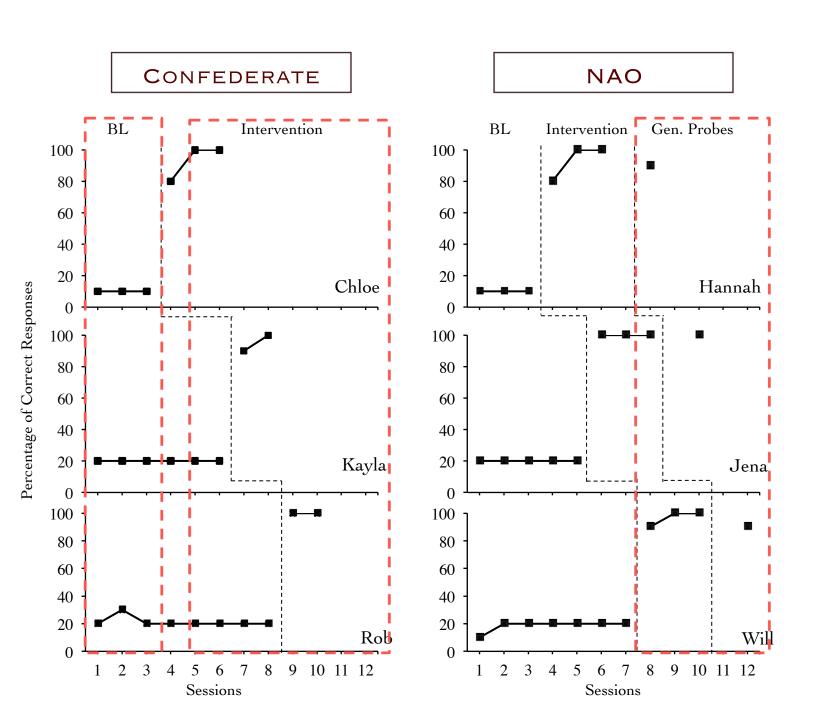


NAO



NAO IN RESEARCH

- Assistant to Direct Staff (Gillesen et al. 2011)
- Skill Acquisition in Children with ASD
 - Imitation (Duquette et al. 2008)
 - Turn-Taking (Robins et al. 2005)
 - Social Skills (Tapus et al. 2012)



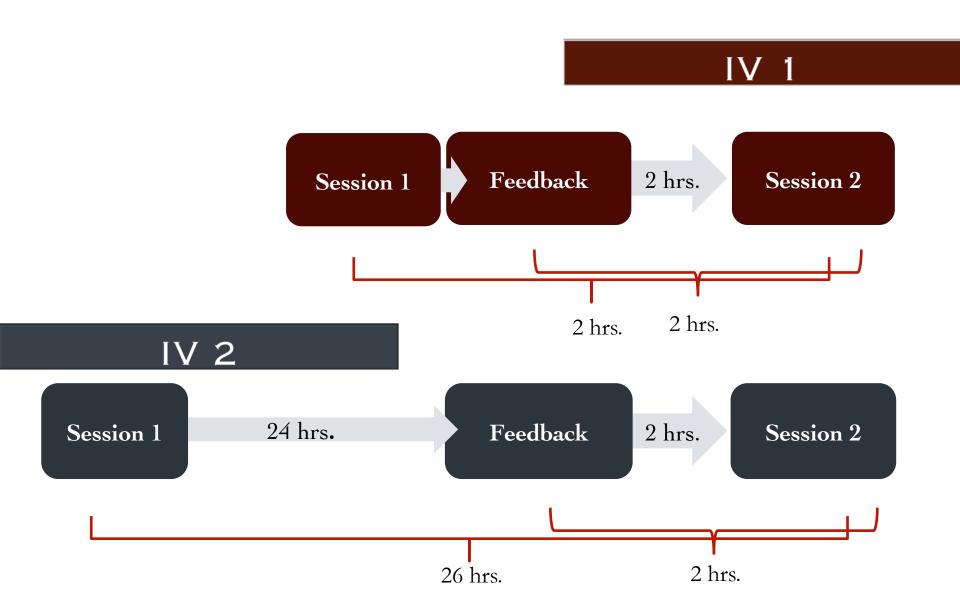
OBJECTIVE & METHOD

- Purpose: Use to isolate effect of 2 schedules of feedback
- Subjects: 6 undergraduate students
- Design: Alternating treatment comparison in a multiple baseline across participants
 - Paired stimulus (PS)
 - Multiple stimulus without replacement (MSWO)

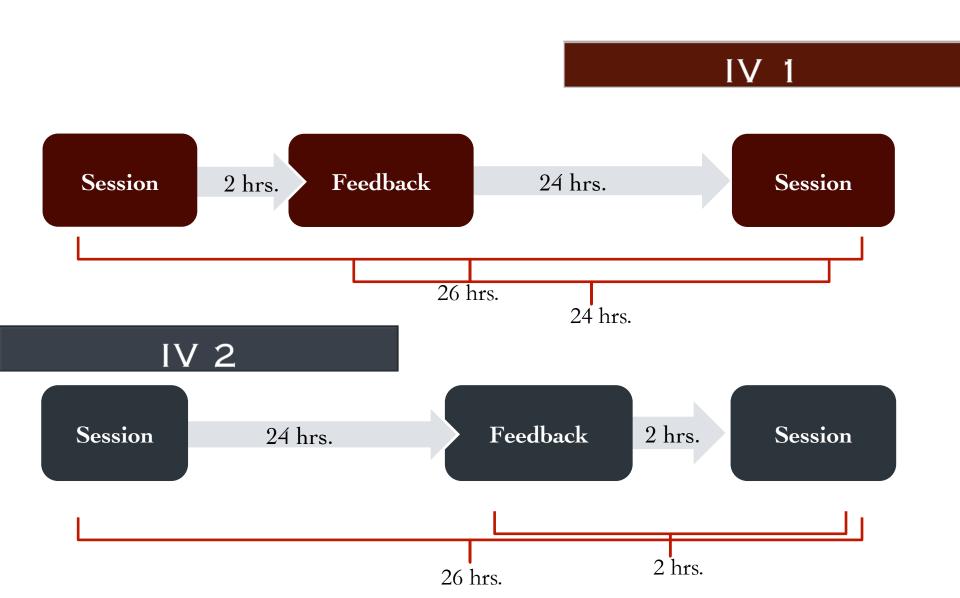
PROCEDURES

- Baseline: Written procedures of DeLeon & Iwata (1996) for MSWO & Fisher et al. (1992) for PS
- Intervention
 - Immediate feedback (i.e., immediately post-session)
 - Delayed feedback (i.e., 24 hrs. post-session)

INTERVENTION: GROUP 1

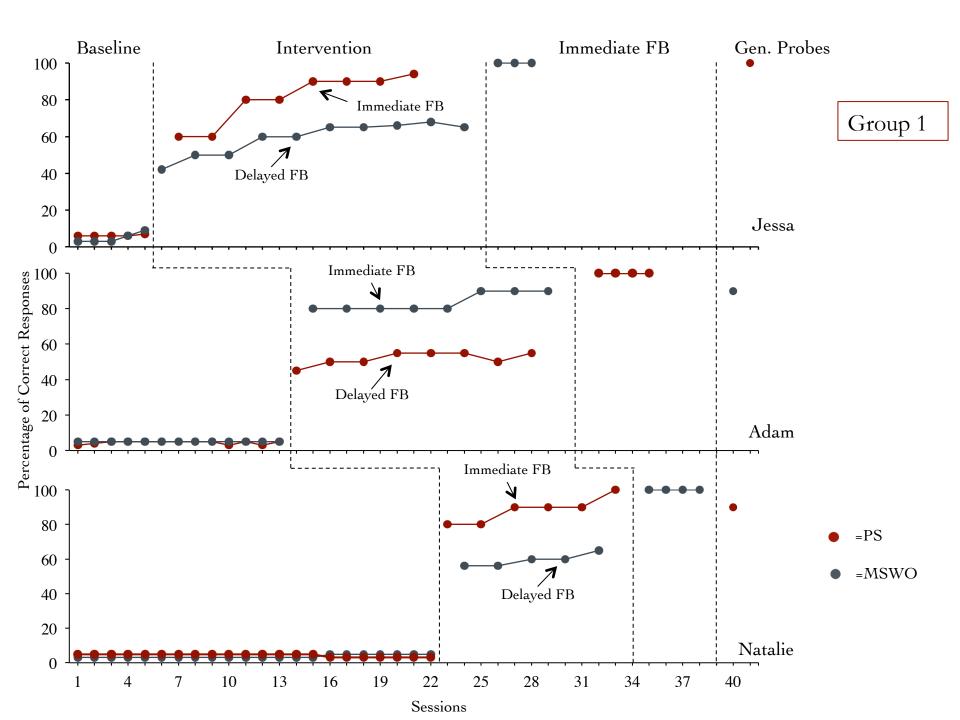


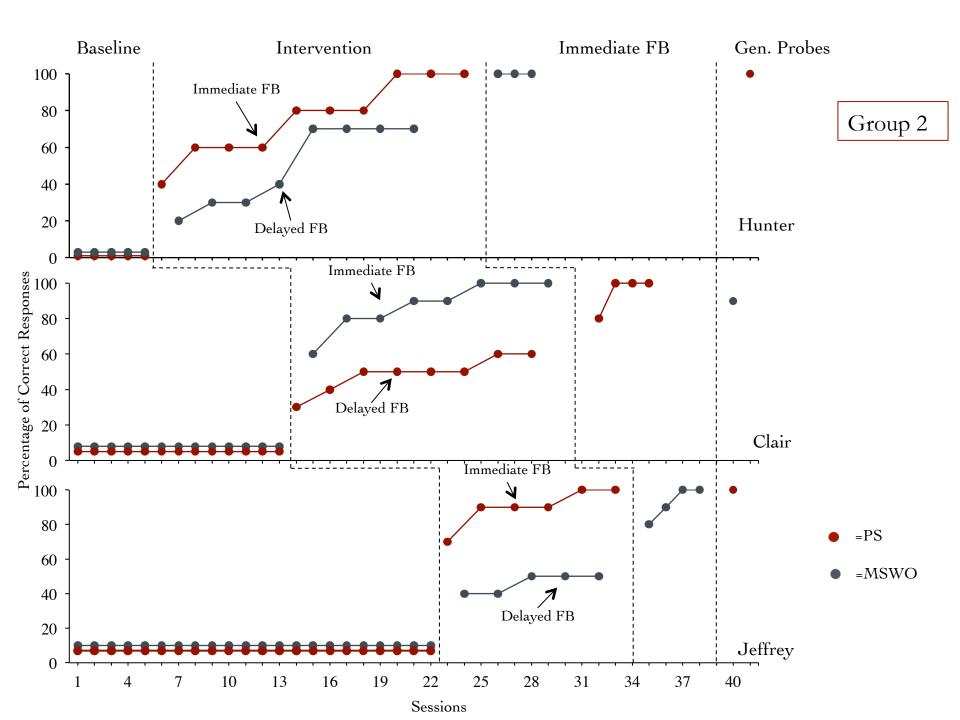
INTERVENTION: GROUP 2



PROCEDURES

- End with most effective treatment
- Generalization probes
 - Confederates
 - Child





ADVANTAGES

- Consistency
- Participant would behave as they would in-vivo
- Not limited by recruitment, training, & turn-over

ADDITIONAL DIRECTIONS

- Variables of Feedback
 - Supplements to feedback (e.g., videos)
 - Schedule of implementing feedback
 - Content of feedback
 - Complexity of task

CHALLENGES

- Constrained repertoire
 - Food refusal
 - Severe forms of SIB
 - Severe forms of aggression
 - Elopement

FUTURE CONSIDERATIONS



Advancements in technology

Developing a precise technology of training & supervision