

TABLE OF INFORMATION FOR 2002

CONSTANTS AND CONVERSION FACTORS		UNITS		PREFIXES				
		Name	Symbol	Factor	Prefix	Symbol		
1 unified atomic mass unit,	$1 \text{ u} = 1.66 \times 10^{-27} \text{ kg}$ $= 931 \text{ MeV}/c^2$	meter	m	$10^9$	giga	G		
Proton mass,	$m_p = 1.67 \times 10^{-27} \text{ kg}$	kilogram	kg	$10^6$	mega	M		
Neutron mass,	$m_n = 1.67 \times 10^{-27} \text{ kg}$	second	s	$10^3$	kilo	k		
Electron mass,	$m_e = 9.11 \times 10^{-31} \text{ kg}$	ampere	A	$10^{-2}$	centi	c		
Magnitude of the electron charge,	$e = 1.60 \times 10^{-19} \text{ C}$	kelvin	K	$10^{-3}$	milli	m		
Avogadro's number,	$N_0 = 6.02 \times 10^{23} \text{ mol}^{-1}$	mole	mol	$10^{-6}$	micro	$\mu$		
Universal gas constant,	$R = 8.31 \text{ J}/(\text{mol} \cdot \text{K})$	hertz	Hz	$10^{-9}$	nano	n		
Boltzmann's constant,	$k_B = 1.38 \times 10^{-23} \text{ J/K}$	newton	N	$10^{-12}$	pico	p		
Speed of light,	$c = 3.00 \times 10^8 \text{ m/s}$	pascal	Pa		VALUES OF TRIGONOMETRIC FUNCTIONS FOR COMMON ANGLES			
Planck's constant,	$h = 6.63 \times 10^{-34} \text{ J}\cdot\text{s}$ $= 4.14 \times 10^{-15} \text{ eV}\cdot\text{s}$	joule	J					
	$hc = 1.99 \times 10^{-25} \text{ J}\cdot\text{m}$ $= 1.24 \times 10^3 \text{ eV}\cdot\text{nm}$	watt	W					
Vacuum permittivity,	$\epsilon_0 = 8.85 \times 10^{-12} \text{ C}^2/\text{N}\cdot\text{m}^2$	coulomb	C					
Coulomb's law constant,	$k = 1/4\pi\epsilon_0 = 9.0 \times 10^9 \text{ N}\cdot\text{m}^2/\text{C}^2$	volt	V					
Vacuum permeability,	$\mu_0 = 4\pi \times 10^{-7}(\text{T}\cdot\text{m})/\text{A}$	ohm	$\Omega$					
Magnetic constant,	$k' = \mu_0/4\pi = 10^{-7}(\text{T}\cdot\text{m})/\text{A}$	henry	H					
Universal gravitational constant,	$G = 6.67 \times 10^{-11} \text{ m}^3/\text{kg}\cdot\text{s}^2$	farad	F					
Acceleration due to gravity at the Earth's surface,	$g = 9.8 \text{ m/s}^2$	tesla	T					
1 atmosphere pressure,	$1 \text{ atm} = 1.0 \times 10^5 \text{ N/m}^2$ $= 1.0 \times 10^5 \text{ Pa}$	degree Celsius	$^\circ\text{C}$					
1 electron volt,	$1 \text{ eV} = 1.60 \times 10^{-19} \text{ J}$	electron-volt	eV					
					$\theta$	$\sin \theta$	$\cos \theta$	$\tan \theta$
					$0^\circ$	0	1	0
					$30^\circ$	$1/2$	$\sqrt{3}/2$	$\sqrt{3}/3$
					$37^\circ$	$3/5$	$4/5$	$3/4$
					$45^\circ$	$\sqrt{2}/2$	$\sqrt{2}/2$	1
					$53^\circ$	$4/5$	$3/5$	$4/3$
					$60^\circ$	$\sqrt{3}/2$	$1/2$	$\sqrt{3}$
					$90^\circ$	1	0	$\infty$

The following conventions are used in this examination.

- I. Unless otherwise stated, the frame of reference of any problem is assumed to be inertial.
- II. The direction of any electric current is the direction of flow of positive charge (conventional current).
- III. For any isolated electric charge, the electric potential is defined as zero at an infinite distance from the charge.
- \*IV. For mechanics and thermodynamics equations,  $W$  represents the work done on a system.

\*Not on the Table of Information for Physics C, since Thermodynamics is not a Physics C topic.

# ADVANCED PLACEMENT PHYSICS B EQUATIONS FOR 2002

NEWTONIAN MECHANICS	ELECTRICITY AND MAGNETISM
$v = v_0 + at$	$a = \text{acceleration}$
$x = x_0 + v_0 t + \frac{1}{2} at^2$	$F = \text{force}$
$v^2 = v_0^2 + 2a(x - x_0)$	$f = \text{frequency}$
$\Sigma \mathbf{F} = \mathbf{F}_{net} = m\mathbf{a}$	$h = \text{height}$
$F_{fric} \leq \mu N$	$J = \text{impulse}$
$a_c = \frac{v^2}{r}$	$K = \text{kinetic energy}$
$\tau = rF \sin \theta$	$k = \text{spring constant}$
$\mathbf{p} = m\mathbf{v}$	$\ell = \text{length}$
$\mathbf{J} = \mathbf{F}\Delta t = \Delta \mathbf{p}$	$m = \text{mass}$
$K = \frac{1}{2}mv^2$	$N = \text{normal force}$
$\Delta U_g = mgh$	$P = \text{power}$
$W = \mathbf{F} \cdot \Delta \mathbf{r} = F\Delta r \cos \theta$	$r = \text{radius or distance}$
$P_{avg} = \frac{W}{\Delta t}$	$\mathbf{r} = \text{position vector}$
$P = \mathbf{F} \cdot \mathbf{v} = Fv \cos \theta$	$T = \text{period}$
$\mathbf{F}_s = -k\mathbf{x}$	$t = \text{time}$
$U_s = \frac{1}{2}kx^2$	$U = \text{potential energy}$
$T_s = 2\pi\sqrt{\frac{m}{k}}$	$v = \text{velocity or speed}$
$T_p = 2\pi\sqrt{\frac{\ell}{g}}$	$W = \text{work done on a system}$
$T = \frac{1}{f}$	$x = \text{position}$
$F_G = -\frac{Gm_1m_2}{r^2}$	$\mu = \text{coefficient of friction}$
$U_G = -\frac{Gm_1m_2}{r}$	$\theta = \text{angle}$
	$\tau = \text{torque}$
	$F = \frac{1}{4\pi\epsilon_0} \frac{q_1q_2}{r^2}$
	$\mathbf{E} = \frac{\mathbf{F}}{q}$
	$U_E = qV = \frac{1}{4\pi\epsilon_0} \frac{q_1q_2}{r}$
	$E_{avg} = -\frac{V}{d}$
	$V = \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{r_i}$
	$C = \frac{Q}{V}$
	$C = \frac{\epsilon_0 A}{d}$
	$U_c = \frac{1}{2} QV = \frac{1}{2} CV^2$
	$I_{avg} = \frac{\Delta Q}{\Delta t}$
	$R = \frac{\rho\ell}{A}$
	$V = IR$
	$P = IV$
	$C_p = \sum_i C_i$
	$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$
	$R_s = \sum_i R_i$
	$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$
	$F_B = qvB \sin \theta$
	$F_B = BIl \sin \theta$
	$B = \frac{\mu_0 I}{2\pi r}$
	$\phi_m = \mathbf{B} \cdot \mathbf{A} = BA \cos \theta$
	$\mathcal{E}_{avg} = -\frac{\Delta\phi_m}{\Delta t}$
	$\mathcal{E} = B\ell v$

## ADVANCED PLACEMENT PHYSICS B EQUATIONS FOR 2002

### FLUID MECHANICS AND THERMAL PHYSICS

$p = p_0 + \rho gh$	$A = \text{area}$
$F_{\text{buoy}} = \rho Vg$	$c = \text{specific heat or molar specific heat}$
$A_1 v_1 = A_2 v_2$	$e = \text{efficiency}$
$p + \rho gy + \frac{1}{2} \rho v^2 = \text{const.}$	$F = \text{force}$
$\Delta \ell = \alpha \ell_0 \Delta T$	$h = \text{depth}$
$Q = mL$	$K_{\text{avg}} = \text{average molecular kinetic energy}$
$Q = mc\Delta T$	$L = \text{heat of transformation}$
$p = \frac{F}{A}$	$\ell = \text{length}$
$pV = nRT$	$M = \text{molecular mass}$
$K_{\text{avg}} = \frac{3}{2} k_B T$	$m = \text{mass of sample}$
$v_{\text{rms}} = \sqrt{\frac{3RT}{M}} = \sqrt{\frac{3k_B T}{\mu}}$	$n = \text{number of moles}$
$W = -p\Delta V$	$p = \text{pressure}$
$Q = nc\Delta T$	$Q = \text{heat transferred to a system}$
$\Delta U = Q + W$	$T = \text{temperature}$
$\Delta U = nc_V \Delta T$	$U = \text{internal energy}$
$e = \left  \frac{W}{Q_H} \right $	$V = \text{volume}$
$e_c = \frac{T_H - T_C}{T_H}$	$v = \text{velocity or speed}$

### ATOMIC AND NUCLEAR PHYSICS

$E = hf = pc$	$E = \text{energy}$
$K_{\text{max}} = hf - \phi$	$f = \text{frequency}$
$\lambda = \frac{h}{p}$	$K = \text{kinetic energy}$
$\Delta E = (\Delta m)c^2$	$m = \text{mass}$

### WAVES AND OPTICS

$v = f\lambda$	$d = \text{separation}$
$n = \frac{c}{v}$	$f = \text{frequency or focal length}$
$n_1 \sin \theta_1 = n_2 \sin \theta_2$	$h = \text{height}$
$\sin \theta_c = \frac{n_2}{n_1}$	$L = \text{distance}$
$\frac{1}{s_i} + \frac{1}{s_0} = \frac{1}{f}$	$M = \text{magnification}$
$M = \frac{h_i}{h_0} = -\frac{s_i}{s_0}$	$m = \text{an integer}$
$f = \frac{R}{2}$	$n = \text{index of refraction}$
$d \sin \theta = m\lambda$	$R = \text{radius of curvature}$
$x_m \approx \frac{m\lambda L}{d}$	$s = \text{distance}$
	$v = \text{speed}$
	$x = \text{position}$
	$\lambda = \text{wavelength}$
	$\theta = \text{angle}$

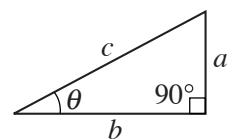
### GEOMETRY AND TRIGONOMETRY

Rectangle	$A = \text{area}$
$A = bh$	$C = \text{circumference}$
Triangle	$V = \text{volume}$
$A = \frac{1}{2} bh$	$S = \text{surface area}$
Circle	$b = \text{base}$
$A = \pi r^2$	$h = \text{height}$
$C = 2\pi r$	$\ell = \text{length}$
Parallelepiped	$w = \text{width}$
$V = \ell wh$	$r = \text{radius}$

Cylinder	$V = \pi r^2 \ell$
	$S = 2\pi r \ell + 2\pi r^2$

Sphere	$V = \frac{4}{3} \pi r^3$
	$S = 4\pi r^2$

Right Triangle	$a^2 + b^2 = c^2$
	$\sin \theta = \frac{a}{c}$
	$\cos \theta = \frac{b}{c}$
	$\tan \theta = \frac{a}{b}$



# ADVANCED PLACEMENT PHYSICS C EQUATIONS FOR 2002

<b>MECHANICS</b>	<b>ELECTRICITY AND MAGNETISM</b>
$v = v_0 + at$	$a = \text{acceleration}$
$x = x_0 + v_0 t + \frac{1}{2} at^2$	$F = \text{force}$
$v^2 = v_0^2 + 2a(x - x_0)$	$f = \text{frequency}$
$\sum \mathbf{F} = \mathbf{F}_{\text{net}} = m\mathbf{a}$	$h = \text{height}$
$\mathbf{F} = \frac{d\mathbf{p}}{dt}$	$I = \text{rotational inertia}$
$\mathbf{J} = \int \mathbf{F} dt = \Delta \mathbf{p}$	$J = \text{impulse}$
$\mathbf{p} = m\mathbf{v}$	$K = \text{kinetic energy}$
$F_{\text{fric}} \leq \mu N$	$k = \text{spring constant}$
$W = \int \mathbf{F} \cdot d\mathbf{r}$	$\ell = \text{length}$
$K = \frac{1}{2} mv^2$	$L = \text{angular momentum}$
$P = \frac{dW}{dt}$	$m = \text{mass}$
$P = \mathbf{F} \cdot \mathbf{v}$	$N = \text{normal force}$
$\Delta U_g = mgh$	$P = \text{power}$
$a_c = \frac{v^2}{r} = \omega^2 r$	$p = \text{momentum}$
$\tau = \mathbf{r} \times \mathbf{F}$	$r = \text{radius or distance}$
$\sum \tau = \tau_{\text{net}} = I\mathbf{a}$	$\mathbf{r} = \text{position vector}$
$I = \int r^2 dm = \sum mr^2$	$T = \text{period}$
$\mathbf{r}_{cm} = \sum m\mathbf{r}/\sum m$	$t = \text{time}$
$v = r\omega$	$U = \text{potential energy}$
$\mathbf{L} = \mathbf{r} \times \mathbf{p} = I\boldsymbol{\omega}$	$v = \text{velocity or speed}$
$K = \frac{1}{2} I\omega^2$	$W = \text{work done on a system}$
$\omega = \omega_0 + \alpha t$	$x = \text{position}$
$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$	$\mu = \text{coefficient of friction}$
$\mathbf{F}_s = -k\mathbf{x}$	$\theta = \text{angle}$
$U_s = \frac{1}{2} kx^2$	$\tau = \text{torque}$
$T = \frac{2\pi}{\omega} = \frac{1}{f}$	$\omega = \text{angular speed}$
$T_s = 2\pi\sqrt{\frac{m}{k}}$	$\alpha = \text{angular acceleration}$
$T_p = 2\pi\sqrt{\frac{\ell}{g}}$	
$\mathbf{F}_G = -\frac{Gm_1m_2}{r^2} \hat{\mathbf{r}}$	
$U_G = -\frac{Gm_1m_2}{r}$	
	$F = \frac{1}{4\pi\epsilon_0} \frac{q_1q_2}{r^2}$
	$\mathbf{E} = \frac{\mathbf{F}}{q}$
	$\oint \mathbf{E} \cdot d\mathbf{A} = \frac{Q}{\epsilon_0}$
	$E = -\frac{dV}{dr}$
	$V = \frac{1}{4\pi\epsilon_0} \sum_i \frac{q_i}{r_i}$
	$U_E = qV = \frac{1}{4\pi\epsilon_0} \frac{q_1q_2}{r}$
	$C = \frac{Q}{V}$
	$C = \frac{\kappa\epsilon_0 A}{d}$
	$C_p = \sum_i C_i$
	$\frac{1}{C_s} = \sum_i \frac{1}{C_i}$
	$I = \frac{dQ}{dt}$
	$U_c = \frac{1}{2} QV = \frac{1}{2} CV^2$
	$R = \frac{\rho\ell}{A}$
	$V = IR$
	$R_s = \sum_i R_i$
	$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$
	$P = IV$
	$\mathbf{F}_M = q\mathbf{v} \times \mathbf{B}$
	$\oint \mathbf{B} \cdot d\mathbf{l} = \mu_0 I$
	$\mathbf{F} = \int I d\mathbf{l} \times \mathbf{B}$
	$B_s = \mu_0 nI$
	$\phi_m = \oint \mathbf{B} \cdot d\mathbf{A}$
	$\mathcal{E} = -\frac{d\phi_m}{dt}$
	$\mathcal{E} = -L \frac{dI}{dt}$
	$U_L = \frac{1}{2} LI^2$

## ADVANCED PLACEMENT PHYSICS C EQUATIONS FOR 2002

### GEOMETRY AND TRIGONOMETRY

Rectangle

$$A = bh$$

Triangle

$$A = \frac{1}{2}bh$$

Circle

$$A = \pi r^2$$

$$C = 2\pi r$$

Parallelepiped

$$V = \ell wh$$

Cylinder

$$V = \pi r^2 \ell$$

$$S = 2\pi r\ell + 2\pi r^2$$

Sphere

$$V = \frac{4}{3}\pi r^3$$

$$S = 4\pi r^2$$

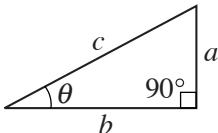
Right Triangle

$$a^2 + b^2 = c^2$$

$$\sin \theta = \frac{a}{c}$$

$$\cos \theta = \frac{b}{c}$$

$$\tan \theta = \frac{a}{b}$$



### CALCULUS

$$\frac{df}{dx} = \frac{df}{du} \frac{du}{dx}$$

$$\frac{d}{dx}(x^n) = nx^{n-1}$$

$$\frac{d}{dx}(e^x) = e^x$$

$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$

$$\frac{d}{dx}(\sin x) = \cos x$$

$$\frac{d}{dx}(\cos x) = -\sin x$$

$$\int x^n dx = \frac{1}{n+1} x^{n+1}, n \neq -1$$

$$\int e^x dx = e^x$$

$$\int \frac{dx}{x} = \ln|x|$$

$$\int \cos x dx = \sin x$$

$$\int \sin x dx = -\cos x$$