# Some examples of exit times

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### 1 Introduction

The theory of Brownian motion allows probabilistic interpretations of solutions to second order differential equations. One such example is the folloging. If D is a regular domain on a manifold M with laplace operator  $\Delta$  then a solution to the differential equation

$$\Delta f = -1$$

on D with boundary condition  $f \equiv 0$  on  $\partial D$  has the probabilistic interpretation  $f(x) = E_x[T_D]$ , where  $E_x$  is the expected value functional on the Wiener space of paths  $\omega$  in M with  $\omega(0) = x$ , and  $T_D$  is the first exit time from D, mamely  $T_D(\omega) = \inf\{t > 0 \mid \omega(t) \notin D\}$  (with the standard convention that the infimum of the empty set is  $\infty$ ). More details on exit times and differential equations can be found in Dynkin [2]; a brief survey in [1, Appendix C].

In this note we study some examples of exits times from domains in the Euclidean and hyperbolic planes. Ghys [3] gave a spectacular aplication of exit times in geometry. The examples here are the base of some exercises in [1, Exercises 2.7.14 C.9.4 and C.9.5], and the calculations were motivated by a discussion on Ghys theorem.

### 2 Cones in the Euclidean plane

In cartesian coordinates (x, y) the euclidean laplacian has the expression

$$\Delta f = f_{xx} + f_{yy}$$

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and in polar coordinates  $(r, \theta)$ 

$$\Delta f = f_{rr} + \frac{1}{r} f_r + \frac{1}{r^2} f_{\theta\theta}.$$

Let C be a cone of opening angle  $2\alpha$  in the euclidean plane. In polar coordinates, C is, up to isometry, the set of those points  $(r, \theta)$  with r > 0 and  $\theta \in [-\alpha, \alpha]$ .

A solution f to the equation  $\triangle f = -1$  in C satisfies

$$f(\lambda x, \lambda y) = \lambda^2 f(x, y),$$

and in polar coordinates:

$$f(\lambda r, \theta) = \lambda^2 f(r, \theta).$$

This says that f is completely determined by the values  $f(1,\theta)$ , and it can be written as  $f(r,\theta) = r^2h(\theta)$ , where h is positive and symmetric on  $[-\alpha,\alpha]$ . Moerover, h satisfies the differential equation

$$h^{\prime\prime} + 4h = -1$$

or in a different way:

$$(h + 1/4)'' + 4(h + 1/4) = 0.$$

The general solution to this equation is of the form

$$h(\theta) = A\cos 2\theta + B\sin 2\theta - 1/4$$
.

The symmetry of h about 0 in  $[-\alpha, \alpha]$  implies that B = 0, and the initial conditions impose that  $A = (1/4)\cos\alpha$ . Therefore,

$$h(\theta) = \frac{-1 + \cos 2\theta}{4\cos 2\alpha}.$$

Because this holds for all  $\theta$  between  $-\alpha/2$  and  $\alpha/2$ , and h > 0, we must have  $\cos 2\alpha > 0$  and with the same sign as  $\cos 2\theta$ . This says that  $\alpha < \pi/4$ , and in this case the solution f exists.

## 3 Domain in the hyperbolic plane

Represent the hyperbolic plane as the set (x, y) with x > 0, endowed with the metric tensor

$$\frac{1}{x^2}(dx \otimes dx + dy \otimes dy).$$

The laplacian  $\triangle_h$  corresponding to this metric tensor is

$$\triangle_h f = x^2 \triangle_e f = x^2 (f_{xx} + f_{yy})$$

and the equation to solve is:

$$f_{xx} + f_{yy} = -x^{-2}$$

with the pertinent initial conditions.

### 3.1 Neighborhoods of geodesics

The first domain to consider is a neighborhood of a geodesic. As all are isometric, it is enough to consider the geodesic y = 0. A tubular neighborhood is precisely a euclidean cone which in polar coordinates we take as  $(r, \theta)$  with  $\theta \in [-\alpha, \alpha]$ , and  $\alpha < \pi/2$ .

As in the previous example, we see that composition with the isometry  $(x, y) \mapsto (\lambda x, \lambda y)$ , leaves the solution f invariant. That is  $f(r, \theta) = f(\theta)$  is a solution to

$$f''(\theta) = \frac{-1}{\cos^2 \theta}$$

and so

$$f(\theta) = \log(\cos \theta / \cos \alpha).$$

#### 3.2 Horoballs

Consider now an horoball. We may assume that it is symmetric with respect to y = 0 and tangent to the point at infinity. The domain is the set of points (x, y) with  $x \ge a > 0$ . As vertical translations are isometries with leave the boundary of this horoball invariant, the solution f of  $\triangle_e f = -x^{-2}$  is invariant under this isometries. That is, f(x + t, y) = f(x, y) for all t. Thus f(x, y) = f(x) dependes only on the horizontal coordinate t. This says that t satisfies the equation

$$f''(x) = -x^{-2}$$

in  $[a, \infty)$ , with f(a) = 0. The minimal solution is

$$f(x) = \log(x/a)$$
.

#### 3.3 Neighborhood of ideal point

The last kind of domain is a neighborhood of a point in the circle at infinity of  $\mathbb{U}$ . Such domain, up to isometry, is of the form  $D = \{(x,y) \mid y \geq 0\}$ . It contains arbitrarely thick neighborhoods of geodesics, hence no such function f exits, that is  $f \equiv \infty$ .

### References

- [1] Alberto Candel and Lawrence Conlon, *Foliations II*, Graduate Studies in Mathematics, Vol. 60, Amer. Math. Soc., Providence, RI, 2003.
- [2] Eugene Dynkin, *Markov Processes*. Grundlehren der mathematischen Wissenschaften Vols. **121**, **122**, Springer, Berlin (1965).
- [3] Étienne Ghys, *Topologie des feuilles génériques*. Ann. Math. **141** (1995), pp. 387–422